

An operator theoretical approach to Riemann-Liouville fractional Cauchy problem

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This paper is concerned with developing an operator theory for Riemann-Liouville fractional Cauchy problem. Two notions, named Riemann-Liouville fractional resolvent and solution operator, are developed. Some of their properties are deduced. Moreover, the obtained results are applied to Riemann-Liouville fractional Cauchy problem.

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1 Introduction and preliminaries

Consider the following Riemann-Liouville α -order abstract Cauchy problem

$$(FAC)_{x,y} \begin{cases} D_t^\alpha u(t) = Au(t), & t > 0, \\ (g_{2-\alpha} * u)(0) = x, & (g_{2-\alpha} * u)'(0) = y, \end{cases}$$

where $1 < \alpha < 2$, $A : D(A) \subset X \rightarrow X$ is a closed densely defined linear operator, $(X, \|\cdot\|)$ is a Banach space, $D(A)$ is the domain of A endowed with the graph norm $\|x\|_{D(A)} = \|x\| + \|Ax\|$, $g_{2-\alpha}(t) = \frac{t^{1-\alpha}}{\Gamma(2-\alpha)}$ for $t > 0$ and $g_{2-\alpha}(t) = 0$ for $t \leq 0$, $x, y \in X$, $*$ is the convolution of functions $g_{2-\alpha}(t) * u(t) = (g_{2-\alpha} * u)(t) = \int_0^t g_{2-\alpha}(t-\sigma)u(\sigma) d\sigma$, D_t^α is the α -order Riemann-Liouville fractional derivative operator which is defined as follows.

Definition 1.1 ([12]) Let $\alpha > 0$, $m = [\alpha]$ denotes the smallest integer greater than or equal to α . The α -order Riemann-Liouville fractional derivative is defined by

$$D_t^\alpha u(t) = \frac{d^m}{dt^m} (g_{m-\alpha} * u)(t) = \frac{d^m}{dt^m} J_t^{m-\alpha} u(t), \quad (1.1)$$

where $u \in L^1((0, T); X)$, $g_{m-\alpha} * u \in W^{m,1}((0, T); X)$, J_t^α is the α -order Riemann-Liouville fractional integral defined by

$$J_t^\alpha u(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-\tau)^{\alpha-1} u(\tau) d\tau. \quad (1.2)$$

When $\alpha = m$, $m \in \mathbb{N}$, define $D_t^m = \frac{d^m}{dt^m}$.

Set $J_t^0 u(t) = u(t)$. The fractional integral operators $\{J_t^\alpha\}_{\alpha \geq 0}$ satisfy the semigroup property

$$J_t^\alpha J_t^\beta = J_t^{\alpha+\beta}, \quad \alpha, \beta \geq 0. \quad (1.3)$$

A strong motivation for studying and investigating the solution and the properties for Riemann-Liouville fractional Cauchy problems comes from the fact that they can be used to model efficiently anomalous diffusion

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on fractals (physical objects of fractional dimension, like some amorphous semiconductors or strongly porous materials; see [1], [10] and the references therein), fractional random walk, etc. Moreover, the observation of a universal response of electromagnetic, acoustic, and mechanical influence shows that the existence of some transfer processes in a medium, which are not described by a usual diffusion equation. In [7]–[9], [11], the authors generalized the diffusion equation by replacing the first time derivative with a fractional derivative of order α :

$$D_t^\alpha u(x, t) = \frac{\partial^2 u(x, t)}{\partial x^2}, \quad 0 \leq \alpha \leq 2,$$

where D_t^α is the Riemann-Liouville fractional derivative operator of order α . These authors proved that the process changes from slow diffusion to classical diffusion, then to diffusion-wave and finally to classical wave when α increases from 0 to 2. The case $\alpha = 1$ corresponds to a parabolic equation, and $\alpha = 2$ is the case of a hyperbolic one.

It is reasonable that the initial condition of $(FAC)_{x,y}$ is expressed in terms of Riemann-Liouville fractional derivatives: on some examples from the field of viscoelasticity, Heymans and Podlubny [5] demonstrated that it is possible to attribute physical meaning to initial conditions expressed in terms of Riemann-Liouville fractional derivatives, and it is possible to obtain initial values for such initial conditions by appropriate measurements; when Riemann-Liouville fractional derivative is applied to describe the constitutive equations of viscoelastic materials, Nutting's Law is

$$\sigma(t) = \nu D_t^\alpha \varepsilon(t),$$

where σ is stress, ε is strain, ν is model constant, Du and Wang pointed out in [3] that in order to describe the physical properties of real viscoelastic materials, initial condition in terms Riemann-Liouville fractional derivatives should be used.

Recently, Peng, Li and Jia [6] were concerned with the special case of α -order abstract Cauchy problem

$$(FAC)_{0,y} \begin{cases} D_t^\alpha u(t) = Au(t), & t > 0, \\ (g_{2-\alpha} * u)(0) = 0, (g_{2-\alpha} * u)'(0) = y. \end{cases}$$

They introduced the notion of strongly continuous fractional resolvent as follows.

Definition 1.2 ([6]) Let $1 < \alpha < 2$. A family $\{S_\alpha(t)\}_{t \geq 0}$ of bounded linear operators of X is called a *strongly continuous fractional resolvent of order α* (or *α -order fractional resolvent*, for short) if it satisfies the following assumptions:

(a) $S_\alpha(t)$ is strongly continuous on R^+ and

$$\lim_{t \rightarrow 0^+} \frac{S_\alpha(t)}{t^{\alpha-1}} x = \frac{1}{\Gamma(\alpha)} x, \quad x \in X,$$

(b) $S_\alpha(t)S_\alpha(s) = S_\alpha(s)S_\alpha(t)$, $s, t \geq 0$,

(c) the equality holds:

$$S_\alpha(s)J_t^\alpha S_\alpha(t) - J_s^\alpha S_\alpha(s)S_\alpha(t) = \frac{s^{\alpha-1}}{\Gamma(\alpha)} J_t^\alpha S_\alpha(t) - \frac{t^{\alpha-1}}{\Gamma(\alpha)} J_s^\alpha S_\alpha(s), \quad t, s \geq 0.$$

Using the above notion, the authors of [6] proved that if the operator A generates an α -order fractional resolvent, then $(FAC)_{0,y}$ has a unique strong solution for $y \in D(A)$ and has a unique weak solution for $y \in X$.

The purpose of this paper is to develop an operator theory to study Riemann-Liouville fractional Cauchy problems $(FAC)_{x,y}$. The arrangement of this paper is as follows. In Section 2, we introduce the notion of Riemann-Liouville fractional resolvent and obtain some of its properties. In Section 3, the solution of fractional abstract Cauchy problem $(FAC)_{x,y}$ is considered. The related notion of solution operator for $(FAC)_{x,0}$ is developed. It is proved that a solution operator is essentially a Riemann-Liouville fractional resolvent. Moreover, an illustrative example, fractional diffuse problem is presented.

Throughout this paper, we always assume $1 < \alpha < 2$, without any additional statement.

2 Riemann-Liouville fractional resolvent

In this section, we introduce the notion of Riemann-Liouville fractional resolvent, and obtain some of its properties.

Definition 2.1 A family $\{T_\alpha(t)\}_{t>0}$ of bounded linear operators is called *Riemann-Liouville α -order fractional resolvent* if it satisfies the following assumptions:

(a) For any $x \in X$, $T_\alpha(\cdot)x \in C((0, \infty), X)$, and

$$\lim_{t \rightarrow 0^+} \Gamma(\alpha - 1)t^{2-\alpha}T_\alpha(t)x = x \quad \text{for all } x \in X; \quad (2.1)$$

(b) $T_\alpha(s)T_\alpha(t) = T_\alpha(t)T_\alpha(s)$ for all $t, s > 0$;

(c) for all $t, s > 0$, there holds

$$T_\alpha(s)J_t^\alpha T_\alpha(t) - J_s^\alpha T_\alpha(s)T_\alpha(t) = \frac{s^{\alpha-2}}{\Gamma(\alpha-1)}J_t^\alpha T_\alpha(t) - \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}J_s^\alpha T_\alpha(s). \quad (2.2)$$

Remark 2.2 The reason why we don't consider the value of $T_\alpha(\cdot)$ at 0 is that the function $t \mapsto \frac{t^{\alpha-1}}{\Gamma(\alpha)}$ exists singularity at 0.

Remark 2.3 By (a) of Definition 2.1, it follows that $T_\alpha(\cdot)x \in L_{loc}^1(\mathbb{R}^+, X)$, for any $x \in X$. In fact, (2.1) implies that there exists $\delta > 0$, such that

$$\|T_\alpha(t)x\| \leq \frac{3}{2} \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} \|x\|, \quad \forall 0 < t < \delta.$$

Thus, for any $\tau_0 > 0$, we have that

$$\int_0^{\tau_0} \|T_\alpha(t)x\| dt \leq \int_0^{\tau_0} \frac{3}{2} \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} dt \|x\| = \frac{3}{2} \frac{\tau_0^{\alpha-1}}{\Gamma(\alpha)} \|x\|, \quad \text{if } \tau_0 \leq \delta,$$

and

$$\begin{aligned} \int_0^{\tau_0} \|T_\alpha(t)x\| dt &= \int_0^\delta \|T_\alpha(t)x\| dt + \int_\delta^{\tau_0} \|T_\alpha(t)x\| dt \\ &\leq \int_0^\delta \frac{3}{2} \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} dt \|x\| + \int_\delta^{\tau_0} \|T_\alpha(t)x\| dt \\ &\leq \frac{3}{2} \frac{\delta^{\alpha-1}}{\Gamma(\alpha)} \|x\| + \int_\delta^{\tau_0} \|T_\alpha(t)x\| dt, \quad \text{if } \tau_0 > \delta. \end{aligned}$$

Therefore, $T_\alpha(\cdot)x \in L_{loc}^1(\mathbb{R}^+, X)$.

Remark 2.4 Define PT_α : for any $x \in X$,

$$(PT_\alpha)(t)x \triangleq \begin{cases} \Gamma(\alpha-1)t^{2-\alpha}T_\alpha(t)x, & t > 0, \\ x, & t = 0. \end{cases}$$

Then, (a) of Definition 2.1 implies that $(PT_\alpha)(\cdot)$ is strongly continuous.

The linear operator A defined by

$$D(A) = \left\{ x \in X : \lim_{t \rightarrow 0^+} \frac{t^{2-\alpha}T_\alpha(t)x - \frac{1}{\Gamma(\alpha-1)}x}{t^\alpha} \text{ exists} \right\}$$

and

$$Ax = \Gamma(2\alpha-1) \lim_{t \rightarrow 0^+} \frac{t^{2-\alpha}T_\alpha(t)x - \frac{1}{\Gamma(\alpha-1)}x}{t^\alpha} \quad \text{for } x \in D(A)$$

is the generator of the Riemann-Liouville α -order fractional resolvent $T_\alpha(t)$, $D(A)$ is the domain of A .

Definition 2.5 The Riemann-Liouville α -order fractional resolvent $\{T_\alpha(t)\}_{t>0}$ is called *exponentially bounded* if there exist constants $M \geq 1, \omega \geq 0$ such that

$$\|T_\alpha(t)\| \leq Me^{\omega t}, \quad t > 0. \tag{2.3}$$

An operator A is said to belong $C^\alpha(M, \omega)$ if A generates an α -order fractional resolvent $T_\alpha(t)$ satisfying (2.3). Denote $C^\alpha(\omega) = \bigcup\{C^\alpha(M, \omega); M \geq 1\}$.

Proposition 2.6 Let $\{T_\alpha(t)\}_{t>0}$ be a Riemann-Liouville α -order fractional resolvent such that $\|T_\alpha(t)\| \leq Me^{\omega t}, t > 0$ for some $M \geq 1, \omega > 0$. Let $R(\lambda) = \int_0^\infty e^{-\lambda t} T_\alpha(t) dt, \lambda > \omega$. Then for $\lambda, \mu > \omega$,

$$\lambda R(\mu) - \mu R(\lambda) = (\lambda^\alpha - \mu^\alpha)R(\mu)R(\lambda). \tag{2.4}$$

Proof. The exponential boundedness implies that $T(\cdot)$ is Laplace transformable. The proof is derived directly by taking Laplace transform with respect to t and s on both sides of (2.2). \square

Proposition 2.7 Let $\{T_\alpha(t)\}_{t>0}$ be a Riemann-Liouville α -order fractional resolvent on X , and A its generator. Then

- (a) $T_\alpha(t)D(A) \subset D(A)$ and $AT_\alpha(t)x = T_\alpha(t)Ax$ for each $x \in D(A)$.
- (b) For each $x \in X, t > 0$,

$$T_\alpha(t)x = \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x + AJ_t^\alpha T_\alpha(t)x. \tag{2.5}$$

- (c) For each $x \in D(A), t > 0$,

$$T_\alpha(t)x = \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x + J_t^\alpha T_\alpha(t)Ax, \tag{2.6}$$

and

$$T_\alpha(\cdot)x \in C^1((0, \infty); X). \tag{2.7}$$

- (d) A is closed and densely defined.

Proof.

- (a) Let $x \in D(A)$, for $t, s > 0$, it follows from $T_\alpha(t)T_\alpha(s) = T_\alpha(s)T_\alpha(t)$ that

$$\frac{s^{2-\alpha}T_\alpha(s)T_\alpha(t)x - \frac{1}{\Gamma(\alpha-1)}T_\alpha(t)x}{s^\alpha} = \frac{T_\alpha(t)\left(s^{2-\alpha}T_\alpha(s)x - \frac{1}{\Gamma(\alpha-1)}x\right)}{s^\alpha},$$

since $T_\alpha(t)$ is bounded linear operator, then

$$\Gamma(2\alpha-1) \lim_{s \rightarrow 0^+} \frac{s^{2-\alpha}T_\alpha(s)T_\alpha(t)x - \frac{1}{\Gamma(\alpha-1)}T_\alpha(t)x}{s^\alpha} = T_\alpha(t)Ax.$$

That is, $T_\alpha(t)x \in D(A)$ and $AT_\alpha(t)x = T_\alpha(t)Ax$.

- (b) For each $x \in X$, we have

$$\begin{aligned} & \left\| \Gamma(2\alpha-1) \frac{J_s^\alpha T_\alpha(s)x}{s^{2\alpha-2}} - x \right\| \\ &= \left\| \frac{\Gamma(2\alpha-1)}{\Gamma(\alpha)} \int_0^s s^{2-2\alpha}(s-\tau)^{\alpha-1} T_\alpha(\tau)x d\tau - x \right\| \\ &= \left\| \frac{\Gamma(2\alpha-1)}{\Gamma(\alpha)} \int_0^1 s^{2-\alpha}(1-\tau)^{\alpha-1} T_\alpha(s\tau)x d\tau - x \right\| \end{aligned}$$

$$\begin{aligned}
 &= \left\| \frac{\Gamma(2\alpha - 1)}{\Gamma(\alpha)\Gamma(\alpha - 1)} \int_0^1 s^{2-\alpha} \Gamma(\alpha - 1)(1 - \tau)^{\alpha-1} T_\alpha(s\tau)x \, d\tau - x \right\| \\
 &= \left\| \frac{\Gamma(2\alpha - 1)}{\Gamma(\alpha)\Gamma(\alpha - 1)} \int_0^1 (1 - \tau)^{\alpha-1} \tau^{\alpha-2} \Gamma(\alpha - 1) \frac{T_\alpha(s\tau)}{(s\tau)^{\alpha-2}} x \, d\tau \right. \\
 &\quad \left. - \frac{\Gamma(2\alpha - 1)}{\Gamma(\alpha)\Gamma(\alpha - 1)} \int_0^1 (1 - \tau)^{\alpha-1} \tau^{\alpha-2} x \, d\tau \right\| \\
 &\leq \frac{\Gamma(2\alpha - 1)}{\Gamma(\alpha)\Gamma(\alpha - 1)} \int_0^1 (1 - \tau)^{\alpha-1} \tau^{\alpha-2} d\tau \sup_{\tau \in [0,1]} \left\| \Gamma(\alpha - 1)(s\tau)^{2-\alpha} T_\alpha(s\tau)x - x \right\| \\
 &\leq \sup_{\tau \in [0,1]} \left\| \Gamma(\alpha - 1)(s\tau)^{2-\alpha} T_\alpha(s\tau)x - x \right\|. \tag{2.8}
 \end{aligned}$$

The combination of (2.8) and (a) of Definition 2.1 implies that

$$\lim_{s \rightarrow 0^+} \Gamma(2\alpha - 1) \frac{J_s^\alpha T_\alpha(s)x}{s^{2\alpha-2}} = x. \tag{2.9}$$

By (c) of Definition 2.1, it follows that

$$\left(T_\alpha(s) - \frac{s^{\alpha-2}}{\Gamma(\alpha - 1)} \right) J_t^\alpha T_\alpha(t)x = J_s^\alpha T_\alpha(s) \left(T_\alpha(t)x - \frac{t^{\alpha-2}}{\Gamma(\alpha - 1)} x \right). \tag{2.10}$$

Thus,

$$\begin{aligned}
 A J_t^\alpha T_\alpha(t)x &= \Gamma(2\alpha - 1) \lim_{s \rightarrow 0^+} \frac{\left(s^{2-\alpha} T_\alpha(s) - \frac{1}{\Gamma(\alpha-1)} \right) J_t^\alpha T_\alpha(t)x}{s^\alpha} \\
 &= \Gamma(2\alpha - 1) \lim_{s \rightarrow 0^+} \frac{J_s^\alpha T_\alpha(s) \left(T_\alpha(t)x - \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x \right)}{s^{2\alpha-2}} \\
 &= T_\alpha(t)x - \frac{t^{\alpha-2}}{\Gamma(\alpha - 1)} x, \tag{2.11}
 \end{aligned}$$

therefore (b) holds.

(c) For any $x \in D(A)$, the limit

$$\lim_{s \rightarrow 0^+} \frac{s^{2-\alpha} T_\alpha(s)x - \frac{1}{\Gamma(\alpha-1)} x}{s^\alpha}$$

exists, then the function

$$g(s) = \frac{s^{2-\alpha} T_\alpha(s)x - \frac{1}{\Gamma(\alpha-1)} x}{s^\alpha}$$

is bounded for sufficiently small $s > 0$. For $t > 0$, by the dominated convergence theorem, we derive

$$\begin{aligned}
 &T_\alpha(t)x - \frac{t^{\alpha-2}}{\Gamma(\alpha - 1)} x \\
 &= A J_t^\alpha T_\alpha(t)x \\
 &= \frac{\Gamma(2\alpha - 1)}{\Gamma(\alpha)} \lim_{s \rightarrow 0^+} \frac{s^{2-\alpha} T_\alpha(s) - \frac{1}{\Gamma(\alpha-1)}}{s^\alpha} \int_0^t (t - \tau)^{\alpha-1} T_\alpha(\tau)x \, d\tau \\
 &= \frac{\Gamma(2\alpha - 1)}{\Gamma(\alpha)} \lim_{s \rightarrow 0^+} \int_0^t (t - \tau)^{\alpha-1} T_\alpha(\tau) \frac{s^{2-\alpha} T_\alpha(s) - \frac{1}{\Gamma(\alpha-1)}}{s^\alpha} x \, d\tau
 \end{aligned}$$

$$\begin{aligned}
&= \frac{\Gamma(2\alpha - 1)}{\Gamma(\alpha)} \int_0^t (t - \tau)^{\alpha-1} T_\alpha(\tau) \lim_{s \rightarrow 0^+} \frac{s^{2-\alpha} T_\alpha(s) - \frac{1}{\Gamma(\alpha-1)}}{s^\alpha} x \, d\tau \\
&= J_t^\alpha T_\alpha(t) Ax.
\end{aligned} \tag{2.12}$$

From (2.12) it follows that $T_\alpha(t)x$ is differentiable on $(0, \infty)$ for all $x \in D(A)$ and

$$\begin{aligned}
\frac{d}{dt} T_\alpha(t)x &= \frac{d}{dt} \left(\frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x + J_t^\alpha T_\alpha(t) Ax \right) \\
&= -\frac{(2-\alpha)t^{\alpha-3}}{\Gamma(\alpha-1)} x + \frac{d}{dt} J_t^\alpha T_\alpha(t) Ax \\
&= -\frac{(2-\alpha)t^{\alpha-3}}{\Gamma(\alpha-1)} x + J_t^{\alpha-1} T_\alpha(t) Ax \\
&= -\frac{(2-\alpha)t^{\alpha-3}}{\Gamma(\alpha-1)} x + \frac{1}{\Gamma(\alpha-1)} \int_0^t (t-\tau)^{\alpha-2} T_\alpha(\tau) Ax \, d\tau \\
&= -\frac{(2-\alpha)t^{\alpha-3}}{\Gamma(\alpha-1)} x + \frac{t^{\alpha-1}}{\Gamma(\alpha-1)} \int_0^1 (1-\tau)^{\alpha-2} T_\alpha(t\tau) Ax \, d\tau.
\end{aligned} \tag{2.13}$$

Now use the dominated convergence theorem to (2.13) to conclude that

$$T_\alpha(\cdot)x \in C^1((0, \infty); X), \quad x \in D(A).$$

(d) Assume that $t > 0$. Let $x_n \in D(A)$, $x_n \rightarrow x$ and $Ax_n \rightarrow y$ as $n \rightarrow \infty$. From part (c), we have

$$\begin{aligned}
T_\alpha(t)x - \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x &= \lim_{n \rightarrow \infty} \left(T_\alpha(t)x_n - \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x_n \right) \\
&= \lim_{n \rightarrow \infty} \frac{1}{\Gamma(\alpha)} \int_0^t (t-\tau)^{\alpha-1} T_\alpha(\tau) Ax_n \, d\tau \\
&= \frac{1}{\Gamma(\alpha)} \int_0^t (t-\tau)^{\alpha-1} T_\alpha(\tau) y \, d\tau \\
&= J_t^\alpha T_\alpha(t) y.
\end{aligned} \tag{2.14}$$

Using (2.9), we have

$$\begin{aligned}
Ax &= \Gamma(2\alpha - 1) \lim_{t \rightarrow 0^+} \frac{t^{2-\alpha} T_\alpha(t)x - \frac{1}{\Gamma(\alpha-1)} x}{t^\alpha} \\
&= \Gamma(2\alpha - 1) \lim_{t \rightarrow 0^+} \frac{J_t^\alpha T_\alpha(t) y}{t^{2\alpha-2}} \\
&= y.
\end{aligned} \tag{2.15}$$

The closeness of A is proved.

For every $x \in X$, set $x_t = J_t^\alpha T_\alpha(t)x$, from (2.11) it follows that $x_t \in D(A)$, and by (2.9) we have $\Gamma(2\alpha - 1)t^{2-2\alpha}x_t \rightarrow x$ as $t \rightarrow 0^+$. Thus $\overline{D(A)} = X$. \square

Theorem 2.8 Let $\{T_\alpha(t)\}_{t>0}$ and $\{S_\alpha(t)\}_{t>0}$ be Riemann-Liouville α -order fractional resolvents with generators A and B respectively. If $A = B$ then $T_\alpha(t) = S_\alpha(t)$ for $t > 0$.

Proof. For $x \in D(A)$, by properties (c), (a) of Proposition 3.7, we obtain

$$\frac{t^{\alpha-2}}{\Gamma(\alpha-2)} * S_\alpha(t)x = (T_\alpha(t) - J_t^\alpha AT_\alpha(t)) * S_\alpha(t)x$$

$$\begin{aligned}
&= T_\alpha(t) * S_\alpha(t)x - g_\alpha(t) * AT_\alpha(t) * S_\alpha(t)x \\
&= T_\alpha(t) * S_\alpha(t)x - g_\alpha(t) * T_\alpha(t) * AS_\alpha(t)x \\
&= T_\alpha(t) * (S_\alpha(t)x - g_\alpha(t) * AS_\alpha(t)x) \\
&= T_\alpha(t) * \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x \\
&= \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} * T_\alpha(t)x,
\end{aligned}$$

by Titchmarsh's theorem, $T_\alpha(t)x = S_\alpha(t)x$ for every $x \in D(A)$, $t \geq 0$, from density of $D(A)$, it follows that $T_\alpha(t) = S_\alpha(t)$. \square

Theorem 2.9 $A \in \mathcal{C}^\alpha(M, \omega)$ if and only if $(\omega^\alpha, \infty) \subset \rho(A)$ and there is a family $\{T_\alpha(t)\}_{t>0}$ of bounded linear operators satisfying

1) for any $x \in X$, $T_\alpha(\cdot)x \in C((0, \infty), X)$, and

$$\lim_{t \rightarrow 0^+} \Gamma(\alpha-1)t^{2-\alpha}T_\alpha(t)x = x \quad \text{for all } x \in X; \quad (2.16)$$

2) $\|T_\alpha(t)\| \leq Me^{\omega t}$, $M \geq 1$, $t > 0$.

3) there holds

$$\lambda R(\lambda^\alpha, A)x = \int_0^\infty e^{-\lambda t} T_\alpha(t)x dt, \quad \lambda > \omega, x \in X. \quad (2.17)$$

If this is the case, $T_\alpha(t)$ is the Riemann-Liouville α -order fractional resolvent generated by A .

Proof. (Necessity) Assume A to be a generator of $\{T_\alpha(t)\}_{t>0}$ such that

$$\|T_\alpha(t)\| \leq Me^{\omega t}, \quad t > 0.$$

Hence $T_\alpha(\cdot)$ is Laplace transformable. Let

$$R(\lambda) = \int_0^\infty e^{-\lambda t} T_\alpha(t) dt, \quad \lambda > \omega > 0. \quad (2.18)$$

Then, by (c) of Proposition 2.7,

$$T_\alpha(t)x = \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x + J_t^\alpha T_\alpha(t)Ax, \quad \forall x \in D(A). \quad (2.19)$$

Taking Laplace transform on both sides of (2.19), we obtain

$$R(\lambda)x = \lambda^{-\alpha+1}x + \lambda^{-\alpha}R(\lambda)Ax = \lambda^{-\alpha+1}x + \lambda^{-\alpha}AR(\lambda)x, \quad \forall x \in D(A), \quad (2.20)$$

where the commutativity of A and $T(\cdot)$ is used. By (d) of Proposition 2.7, A is dense in X . This implies that

$$R(\lambda) = \lambda^{-\alpha+1} + \lambda^{-\alpha}AR(\lambda) \quad \text{on } X. \quad (2.21)$$

Hence

$$\frac{R(\lambda)}{\lambda}(\lambda^\alpha - A)x = x$$

and

$$(\lambda^\alpha - A)\frac{R(\lambda)}{\lambda} = I \quad \text{on } X.$$

This implies that $(\omega^\alpha, \infty) \in \rho(A)$ and

$$R(\lambda) = \lambda(\lambda^\alpha - A)^{-1}. \quad (2.22)$$

(Sufficiency) By (2.17), we derive that

$$R(\lambda^\alpha, A) = \frac{R(\lambda)}{\lambda}.$$

Using resolvent identify related to operator A as follows

$$R(\lambda^\alpha, A) - R(\mu^\alpha, A) = (\mu^\alpha - \lambda^\alpha)R(\lambda^\alpha, A) - R(\mu^\alpha, A),$$

we obtain that

$$\frac{R(\lambda)}{\lambda} - \frac{R(\mu)}{\mu} = (\mu^\alpha - \lambda^\alpha) \frac{R(\lambda)}{\lambda} \frac{R(\mu)}{\mu}.$$

By virtue of Laplace transform, we obtain

$$T_\alpha(s)J_t^\alpha T_\alpha(t) - J_s^\alpha T_\alpha(s)T_\alpha(t) = \frac{s^{\alpha-2}}{\Gamma(\alpha-1)} J_t^\alpha T_\alpha(t) - \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} J_s^\alpha T_\alpha(s) \tag{2.23}$$

for all $t, s > 0$. □

Below we shall relate Riemann-Liouville α -order fractional resolvent to α -order fractional resolvent defined by Li, Peng and Jia [6]. To this end, we first study the relationship of Riemann-Liouville α -order fractional resolvent and solution operator of the following fractional differential equation

$$\begin{cases} D_t^\alpha [u(t) - x] = Au(t), & t > 0, \\ u(0) = x, \quad u'(0) = 0. \end{cases} \tag{2.24}$$

Here the solution operator of the above system is defined by

Definition 2.10 ([2]) A family $\{T(t)\}_{t \geq 0}$ of bounded linear operators of X is called a *solution operator for system (2.24)* if the following three conditions are satisfied:

- (a) $T(t)$ is strongly continuous for $t \geq 0$ and $T(0) = I$,
- (b) $T(t)D(A) \subset D(A)$ and $AT(t)x = T(t)Ax$ for all $x \in D(A)$ and $t \geq 0$,
- (c) for any $x \in D(A)$, there holds

$$T(t)x = x + J_t^\alpha T(t)Ax, \quad t \geq 0.$$

Theorem 2.11 Assume that A generates a Riemann-Liouville α -order fractional resolvent $\{T_\alpha(t)\}_{t > 0}$ on X . Then, there exists a solution operator $\{S_\alpha(t)\}_{t \geq 0}$ for (2.24).

Proof. Define $S_\alpha(t) = J_t^{2-\alpha} T_\alpha(t)$, $t > 0$. For any $y \in X$,

$$\begin{aligned} \lim_{t \rightarrow 0^+} S_\alpha(t)y &= \lim_{t \rightarrow 0^+} J_t^{2-\alpha} T_\alpha(t)y \\ &= \frac{1}{\Gamma(2-\alpha)} \lim_{t \rightarrow 0^+} \int_0^t (t-\sigma)^{1-\alpha} T_\alpha(\sigma)y \, d\sigma \\ &= \frac{1}{\Gamma(2-\alpha)} \lim_{t \rightarrow 0^+} \int_0^t (t-\sigma)^{1-\alpha} T_\alpha(\sigma)y \, d\sigma \\ &= \frac{1}{\Gamma(2-\alpha)} \lim_{t \rightarrow 0^+} \int_0^1 t^{2-\alpha} (1-\sigma)^{1-\alpha} T_\alpha(t\sigma)y \, d\sigma \\ &= \frac{1}{\Gamma(2-\alpha)} \lim_{t \rightarrow 0^+} \int_0^1 \sigma^{\alpha-2} (1-\sigma)^{1-\alpha} (t\sigma)^{2-\alpha} T_\alpha(t\sigma)y \, d\sigma. \end{aligned}$$

By dominated convergence theorem, it follows that

$$\begin{aligned} \lim_{t \rightarrow 0^+} S_\alpha(t)y &= \lim_{t \rightarrow 0^+} J_t^{2-\alpha} T_\alpha(t)y \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{\Gamma(2-\alpha)\Gamma(\alpha-1)} \int_0^1 \sigma^{\alpha-2}(1-\sigma)^{1-\alpha} \lim_{t \rightarrow 0^+} \Gamma(\alpha-1)(t\sigma)^{2-\alpha} T_\alpha(t\sigma)y \, d\sigma \\
&= \frac{1}{\Gamma(2-\alpha)\Gamma(\alpha-1)} \int_0^1 \sigma^{\alpha-2}(1-\sigma)^{1-\alpha} y \, d\sigma \\
&= y.
\end{aligned} \tag{2.25}$$

This means that we can define $S_\alpha(0) = I$. Then, $\{S_\alpha(t)\}_{t \geq 0}$ is strongly continuous with $S_\alpha(0) = I$.

For any $x \in D(A)$, by (a) of Proposition 2.7, $T_\alpha(\cdot)x \in C((0, \infty), D(A))$

$$T_\alpha(t)x = \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x + J_t^\alpha T_\alpha(t)Ax. \tag{2.26}$$

Taking $2-\alpha$ times integral on both sides of (2.26), we obtain

$$\begin{aligned}
J_t^{2-\alpha} T_\alpha(t)x &= (g_{2-\alpha} * T_\alpha(\cdot)x)(t) \\
&= J_t^{2-\alpha} \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x + J_t^{2-\alpha} J_t^\alpha T_\alpha(t)Ax \\
&= x + J_t^\alpha J_t^{2-\alpha} T_\alpha(t)Ax,
\end{aligned}$$

that is,

$$S_\alpha(t)x = x + J_t^\alpha S_\alpha(t)Ax, \quad t > 0. \tag{2.27}$$

By the definition of $S_\alpha(0)$, we derive that (2.27) holds indeed for $t \geq 0$. Therefore, by Definition 2.10, $\{S_\alpha(t)\}_{t \geq 0}$ is an α -resolvent operator function generated by A . The proof is completed. \square

Combining Theorem 2.11 with Proposition 3.14 of [6], we derive the following theorem.

Theorem 2.12 Assume that A generates a Riemann-Liouville α -order fractional resolvent $\{T_\alpha(t)\}_{t > 0}$ on X . Then, A is the generator of an α -order fractional resolvent defined by [6].

3 Fractional Cauchy problem

This section is set to discussing the solution of fractional abstract Cauchy problem $(FAC)_{x,y}$. A related notion, named solution operator for $(FAC)_{x,0}$ is developed. It is proved that a solution operator is essentially a Riemann-Liouville fractional resolvent. Moreover, an illustrative example, fractional diffuse problem is presented.

Definition 3.1 A family $\{T_\alpha(t)\}_{t > 0}$ of bounded linear operators of X is called a *solution operator* for $(FAC)_{x,0}$ if the following three conditions are satisfied:

- (a) for any $x \in X$, $T_\alpha(\cdot)x \in C((0, \infty), X)$, and

$$\lim_{t \rightarrow 0^+} \Gamma(\alpha-1)t^{2-\alpha} T_\alpha(t)x = x \quad \text{for all } x \in X; \tag{3.1}$$

- (b) $T_\alpha(t)D(A) \subset D(A)$ and $AT_\alpha(t)x = T_\alpha(t)Ax$ for all $x \in D(A)$ and $t > 0$,

- (c) for any $x \in D(A)$, there holds

$$T_\alpha(t)x = \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x + J_t^\alpha T_\alpha(t)Ax, \quad t > 0.$$

By Proposition 2.7, it follows that a Riemann-Liouville α -order fractional resolvent is a solution operator for $(FAC)_{x,0}$. On the other hand, assume that $\{T_\alpha(t)\}_{t > 0}$ is a solution operator for $(FAC)_{x,0}$. For $x \in D(A)$, we have

$$\frac{t^{\alpha-2}}{\Gamma(\alpha-1)} * [T_\alpha(s)T_\alpha(t)x] = (T_\alpha(t) - J_t^\alpha AT_\alpha(t)) * [T_\alpha(s)T_\alpha(t)x]$$

$$\begin{aligned}
 &= T_\alpha(t) * [T_\alpha(s)T_\alpha(t)x - J_t^\alpha AT_\alpha(s)T_\alpha(t)x] \\
 &= T_\alpha(t) * \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} T_\alpha(s)x \\
 &= \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} * [T_\alpha(t)T_\alpha(s)x], \quad t, s > 0.
 \end{aligned}$$

By Titchmarsh’s theorem, $T_\alpha(s)T_\alpha(t)x = T_\alpha(t)T_\alpha(s)x$ for every $x \in D(A)$, $t, s \geq 0$. By the densely-definedness of $D(A)$, it follows that $T_\alpha(s)T_\alpha(t) = T_\alpha(t)T_\alpha(s)$.

Since A is closed densely defined, we derive that for any $x \in X$,

$$T_\alpha(s)x = \frac{s^{\alpha-2}}{\Gamma(\alpha-1)}x + AJ_s^\alpha T_\alpha(s)x, \quad t > 0. \tag{3.2}$$

Replace x with $J_t^\alpha T_\alpha(t)x$, we obtain

$$\begin{aligned}
 &T_\alpha(s)J_t^\alpha T_\alpha(t)x \\
 &= \frac{s^{\alpha-2}}{\Gamma(\alpha-1)} J_t^\alpha T_\alpha(t)x + AJ_s^\alpha T_\alpha(s)J_t^\alpha T_\alpha(t)x \\
 &= \frac{s^{\alpha-2}}{\Gamma(\alpha-1)} J_t^\alpha T_\alpha(t)x + AJ_t^\alpha T_\alpha(t)J_s^\alpha T_\alpha(s)x \\
 &= \frac{s^{\alpha-2}}{\Gamma(\alpha-1)} J_t^\alpha T_\alpha(t)x + T_\alpha(t)J_s^\alpha T_\alpha(s)x - \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} J_s^\alpha T_\alpha(s)x, \quad t, s > 0,
 \end{aligned}$$

which indicates that (2.2) holds. Hence, $\{T_\alpha(t)\}_{t>0}$ is a Riemann-Liouville α -order fractional resolvent. So we have

Theorem 3.2 A family $\{T_\alpha(t)\}_{t>0}$ of bounded linear operators is a solution operator for $(FAC)_{x,0}$ if and only if it is a Riemann-Liouville α -order fractional resolvent.

Definition 3.3 A function $u \in C((0, \infty), X)$ is called a *strong solution* of $(FAC)_{x,0}$ if $u \in C((0, \infty), D(A))$, $J^{2-\alpha}u \in C^2((0, \infty), X)$ and $(FAC)_{x,0}$ holds.

Definition 3.4 A function $u \in C((0, \infty), X)$ is called a *mild solution* of $(FAC)_{x,0}$ if $J_t^\alpha u(t) \in D(A)$, and $u(t) = \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x + AJ_t^\alpha u(t)$, $t > 0$.

Theorem 3.5 Assume that $\{T_\alpha(t)\}_{t>0}$ is the Riemann-Liouville α -order fractional resolvent generated by A , then

- i) For every $x \in D(A)$, $T_\alpha(\cdot)x$ is the strong solution of $(FAC)_{x,0}$;
- ii) for every $x \in X$, $T_\alpha(\cdot)x$ is the mild solution of $(FAC)_{x,0}$.

Proof. For any $x \in D(A)$, by (a) of Proposition 2.7, $T_\alpha(\cdot)x \in C((0, \infty), D(A))$

$$T_\alpha(t)x = \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x + J_t^\alpha T_\alpha(t)Ax. \tag{3.3}$$

Taking $2 - \alpha$ times integral on both sides of (3.3) and observe that

$$\lim_{t \rightarrow 0^+} J_t^{2-\alpha} T_\alpha(t) = 0,$$

we obtain

$$\begin{aligned}
 J_t^{2-\alpha} T_\alpha(t)x &= (g_{2-\alpha} * T_\alpha(\cdot)x)(t) \\
 &= J_t^{2-\alpha} \frac{t^{\alpha-2}}{\Gamma(\alpha-1)}x + J_t^{2-\alpha} J_t^\alpha T_\alpha(t)Ax
 \end{aligned}$$

$$\begin{aligned}
&= x + J_t^\alpha J_t^{2-\alpha} T_\alpha(t) Ax \\
&= x + J_\alpha^2 T_\alpha(t) Ax.
\end{aligned}$$

Hence, $(g_{2-\alpha} * T_\alpha(\cdot)x)(0) = x$, $J_t^{2-\alpha} T_\alpha(\cdot)x \in C^2((0, \infty), X)$,

$$\begin{aligned}
\left. \frac{d}{dt} (g_{2-\alpha} * T_\alpha(\cdot)x)(t) \right|_{t=0} &= \left. \frac{d}{dt} (x + J_\alpha^2 T_\alpha(t) Ax) \right|_{t=0} \\
&= \left. \int_0^t T_\alpha(\sigma) Ax \, d\sigma \right|_{t=0} \\
&= 0,
\end{aligned}$$

and

$$\begin{aligned}
D_t^\alpha T_\alpha(t)x &= D_t^\alpha \left(\frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x \right) + D_t^\alpha J_t^\alpha T_\alpha(t) Ax \\
&= \frac{d^2}{dt^2} J_t^{2-\alpha} \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x + T_\alpha(t) Ax \\
&= T_\alpha(t) Ax \\
&= AT_\alpha(t)x.
\end{aligned}$$

This completes the proof of i). ii) can be obtained directly from the definition and Theorem 3.2. \square

Definition 3.6 A function $u \in C((0, \infty), X)$ is called a *strong solution* of $(FAC)_{x,y}$ if $u \in C((0, \infty), D(A))$, $J^{2-\alpha} u \in C^2((0, \infty), X)$ and $(FAC)_{x,y}$ holds.

Definition 3.7 A function $u \in C((0, \infty), X)$ is called a *mild solution* of $(FAC)_{x,y}$ if $J_t^\alpha u(t) \in D(A)$, and $u(t) = \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x + \frac{t^{\alpha-1}}{\Gamma(\alpha)} y + AJ_t^\alpha u(t)$, $t > 0$.

Theorem 3.8 Assume that $\{T_\alpha(t)\}_{t>0}$ is the Riemann-Liouville α -order fractional resolvent generated by A , then

- i) For every $x, y \in D(A)$, $T_\alpha(\cdot)x + \int_0^\cdot T_\alpha(\sigma)y \, d\sigma$ is the strong solution of $(FAC)_{x,y}$;
- ii) for every $x, y \in X$, $T_\alpha(\cdot)x + \int_0^\cdot T_\alpha(\sigma)y \, d\sigma$ is the mild solution of $(FAC)_{x,y}$.

Proof.

- i) For any $x \in D(A)$, by (a) of Proposition 2.7, $T_\alpha(\cdot)x \in C((0, \infty), D(A))$. By (b) of Proposition 2.7, it follows that,

$$\begin{aligned}
&T_\alpha(t)x + \int_0^t T_\alpha(\sigma)y \, d\sigma \\
&= \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x + \frac{t^{\alpha-1}}{\Gamma(\alpha)} y + J_t^\alpha \left(T_\alpha(t) Ax + \int_0^t T_\alpha(\sigma) \, d\sigma Ay \right). \tag{3.4}
\end{aligned}$$

Taking $2 - \alpha$ times integral on both sides of (3.4), we obtain

$$\begin{aligned}
&J_t^{2-\alpha} \left(T_\alpha(t)x + \int_0^t T_\alpha(\sigma)y \, d\sigma \right) \\
&= \left(g_{2-\alpha} * \left(T_\alpha(\cdot)x + \int_0^\cdot T_\alpha(\sigma)y \, d\sigma \right) \right)(t) \\
&= J_t^{2-\alpha} \left(\frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x + \frac{t^{\alpha-1}}{\Gamma(\alpha)} y \right) + J_t^{2-\alpha} J_t^\alpha \left(T_\alpha(t) Ax + \int_0^t T_\alpha(\sigma) \, d\sigma Ay \right)
\end{aligned}$$

$$\begin{aligned}
 &= J_t^{2-\alpha} \left(\frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x + \frac{t^{\alpha-1}}{\Gamma(\alpha)} y \right) + J_t^\alpha J_t^{2-\alpha} \left(T_\alpha(t)Ax + \int_0^t T_\alpha(\sigma) d\sigma Ay \right) \\
 &= x + ty + J_t^2 T_\alpha(t)Ax + J_t^3 T_\alpha(t)Ay.
 \end{aligned}$$

Observe that by (2.25), $\lim_{t \rightarrow 0^+} J_t^{2-\alpha} T_\alpha(t) = I$. Hence, $(g_{2-\alpha} * (T_\alpha(\cdot)x + \int_0^\cdot T_\alpha(\sigma)y d\sigma))(0) = x$, $J_t^{2-\alpha} (T_\alpha(\cdot)x + \int_0^\cdot T_\alpha(\sigma) d\sigma) \in C^2((0, \infty), X)$,

$$\begin{aligned}
 &\frac{d}{dt} \left(g_{2-\alpha} * \left(T_\alpha(\cdot)x + \int_0^\cdot T_\alpha(\sigma)y d\sigma \right) \right) \Big|_{t=0} \\
 &= \frac{d}{dt} [x + ty + J_t^2 T_\alpha(t)Ax + J_t^3 T_\alpha(t)Ay] \Big|_{t=0} \\
 &= y + \int_0^t T_\alpha(\sigma)Ax d\sigma \Big|_{t=0} + \int_0^t (t-\sigma)T_\alpha(\sigma)Ay d\sigma \Big|_{t=0} \\
 &= y,
 \end{aligned}$$

and

$$\begin{aligned}
 &D_t^\alpha \left(T_\alpha(t)x + \int_0^t T_\alpha(\sigma)y d\sigma \right) \\
 &= D_t^\alpha \left(\frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x + \frac{t^{\alpha-1}}{\Gamma(\alpha)} y \right) + D_t^\alpha J_t^\alpha T_\alpha(t)Ax + D_t^\alpha J_t^\alpha \int_0^t T_\alpha(\sigma) d\sigma Ay \\
 &= \frac{d^2}{dt^2} [x + ty + J_t^2 T_\alpha(t)Ax + J_t^3 T_\alpha(t)Ay] \\
 &= T_\alpha(t)Ax + \int_0^t T_\alpha(\sigma) d\sigma Ay \\
 &= A \left(T_\alpha(t)x + \int_0^t T_\alpha(\sigma)y d\sigma \right).
 \end{aligned}$$

ii) since A is closed and densely defined, for any $x, y \in X$, by (3.4), it follows that

$$\begin{aligned}
 &T_\alpha(t)x + \int_0^t T_\alpha(\sigma)y d\sigma \\
 &= \frac{t^{\alpha-2}}{\Gamma(\alpha-1)} x + \frac{t^{\alpha-1}}{\Gamma(\alpha)} y + A J_t^\alpha \left(T_\alpha(t)x + \int_0^t T_\alpha(\sigma) d\sigma y \right).
 \end{aligned}$$

□

Example 3.9 Let $\alpha \in (1, 2)$. Consider the following fractional diffuse problem

$$(FDE)_{f,g} \begin{cases} D_t^\alpha u(t, x) = \frac{\partial^2}{\partial x^2} u(t, x), & 0 < x < 1, t > 0, \\ u(t, 0) = u(t, 1) = 0, \\ (g_{2-\alpha}(t) * u(t, x))|_{t=0} = f(x), & \frac{\partial u}{\partial t} (g_{2-\alpha}(t) * u(t, x))|_{t=0} = g(x). \end{cases}$$

Take $X = L^2(0, 1)$, $A = \frac{\partial^2}{\partial x^2}$ with domain $D(A) = \{\varphi \in W^{2,2}(0, 1), \varphi(0) = \varphi(1) = 0\}$. It is easy to see that A has eigenvalues $-n^2\pi^2$ with eigenfunctions $\sin n\pi x$, $n \in \mathbb{N}$. For any $f \in X$, there exists $\{f_n\}_{n \in \mathbb{N}}$ such that $f(x) = \sum_{n=1}^\infty f_n \sin n\pi x$. We define the family $\{T_\alpha(t)\}_{t>0}$ by

$$(T_\alpha(t)f)(x) = \sum_{n=1}^\infty t^{\alpha-2} E_{\alpha, \alpha-1}(-n^2\pi^2 t^\alpha) f_n \sin n\pi x,$$

where $E_{\alpha, \alpha-1}$ is the Mittag-Leffler function defined by

$$E_{\alpha, \alpha-1}(z) = \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(\alpha k + \alpha - 1)}, \quad z \in \mathbb{C}.$$

The Mittag-Leffler function $E_{\alpha, \alpha-1}$ is related to the Laplace integral

$$\int_0^{\infty} e^{-\lambda t} t^{\alpha-2} E_{\alpha, \alpha-1}(\omega t^{\alpha}) dt = \frac{\lambda}{\lambda^{\alpha} - \omega}, \quad \operatorname{Re} \lambda > |\omega|^{1/\alpha}.$$

For more information about Mittag-Leffler function, we refer to [4], [12]. We shall show that $\{T(t)\}_{t>0}$ is a Riemann-Liouville fractional resolvent.

a) Obversely, $T(\cdot)f \in C((0, \infty), X)$. Moreover,

$$\begin{aligned} \Gamma(\alpha - 1)t^{2-\alpha}T_{\alpha}(t)f &= \sum_{n=1}^{\infty} \Gamma(\alpha - 1)E_{\alpha, \alpha-1}(-n^2\pi^2t^{\alpha})c_n \sin(n\pi \cdot) \\ &\rightarrow f \text{ (as } t \rightarrow 0^+) \text{ in } X. \end{aligned}$$

b) The commutativity of $T_{\alpha}(t)$ and $T_{\alpha}(s)$, $t, s > 0$ is obtained directly by the definition of $\{T_{\alpha}(t)\}_{t>0}$.

c) Through simple calculate, we obtain the Laplace transform of $\hat{T}_{\alpha}(\lambda)$ by

$$\hat{T}_{\alpha}(\lambda)f = \sum_{n=1}^{\infty} \frac{\lambda^{\alpha}}{\lambda} + n^2\pi^2 f_n \sin(n\pi \cdot).$$

Assume that $f \in D(A)$ such that

$$\lambda f - Af = g, \quad \lambda \in \rho(A).$$

Then, $f = \sum_{n=0}^{\infty} f_n \sin(n\pi \cdot)$, and

$$\sum_{n=0}^{\infty} (\lambda + n^2\pi^2) f_n \sin(n\pi \cdot) = \sum_{n=0}^{\infty} g_n \sin(n\pi \cdot), \quad \lambda \in \rho(A).$$

This indicates that

$$R(\lambda, A)g = \sum_{n=0}^{\infty} \frac{g_n}{\lambda + n^2\pi^2} \sin(n\cdot), \quad \lambda \in \rho(A)$$

and

$$\lambda R(\lambda^{\alpha}, A)g = \sum_{n=0}^{\infty} \frac{\lambda g_n}{\lambda^{\alpha} + n^2\pi^2} \sin(n\pi \cdot), \quad (3.5)$$

for any $\lambda^{\alpha} \in \rho(A)$, $x \in X$. Hence

$$\lambda R(\lambda^{\alpha}, A)g = \int_0^{\infty} e^{-\lambda t} T_{\alpha}(t)g dt, \quad \lambda > \omega, \quad g \in X.$$

Observe that A is closed and densely defined. By Theorem 2.9, it follows that $\{T_{\alpha}(t)\}_{t>0}$ is a Riemann-Liouville fractional resolvent generated by A . Theorem 3.8 implies that

$$\begin{aligned} T_{\alpha}(t)f + \int_0^t T_{\alpha}(\sigma)g d\sigma \\ = \sum_{n=1}^{\infty} [t^{\alpha-2}E_{\alpha, \alpha-1}(-n^2\pi^2t^{\alpha})f_n + t^{\alpha-1}E_{\alpha, \alpha}(-n^2\pi^2t^{\alpha})g_n] \sin(n\pi \cdot) \end{aligned}$$

is the solution of $(FDE)_{f,g}$.

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