

Supplementary Material for “Intrinsic Tensor Sparsity Regularization and Its Applications to Tensor Recovery”

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Abstract—In this supplementary material, we provide the proofs to Theorems 1 presented in the maintext. We also present more clarifications on the parameter settings in our experiment.

Index Terms—proofs to Theorems, parameter settings.

1 PROOF TO THEOREM 1

In this section we propose the proof of Theorem 1.

Theorem 1. For sequences $\{\mathcal{S}^{(l)}\}$, $\{\mathcal{M}_k^{(l)}\}$ and $\{U_k^{(l)}\}$, $k = 1, 2, \dots, N$, generated by Algorithm 1 and $\mathcal{X}^{(l)} = \mathcal{S}^{(l)} \times_1 U_1^{(l)} \times_2 \dots \times_N U_N^{(l)}$, $\{\mathcal{M}_k^{(l)}\}$ and $\{\mathcal{X}^{(l)}\}$ satisfy:

$$\begin{aligned} \|\mathcal{X}^{(l)} - \mathcal{M}_k^{(l)}\|_F &\leq O(\mu^{(l)} \rho^{-l/2}), \\ \|\mathcal{X}^{(l+1)} - \mathcal{X}^{(l)}\|_F &\leq O(\mu^{(l)} \rho^{-l/2}). \end{aligned} \quad (1)$$

Proof. We first proof that when $\lim_{l \rightarrow \infty} a^{(l)} = 0$,

$$|x - D_{a^{(l)}, \varepsilon}(x)| \leq O((a^{(l)})^{\frac{1}{2}}). \quad (2)$$

Based on the definition of $D_{a^{(l)}, \varepsilon}$ defined by (??), we can obtain that if $|x| < 2\sqrt{a^{(l)}} - \varepsilon$ we have

$$|x - D_{a^{(l)}, \varepsilon}(x)| = |x| < 2\sqrt{a^{(l)}} - \varepsilon \leq O((a^{(l)})^{\frac{1}{2}}), \quad (3)$$

and if $|x| \geq 2\sqrt{a^{(l)}} - \varepsilon$, we have

$$\begin{aligned} |x - D_{a^{(l)}, \varepsilon}(x)| &= \frac{|x| + \varepsilon - \sqrt{(|x| + \varepsilon)^2 - 4a^{(l)}}}{2} \\ &= a^{(l)} + O((a^{(l)})^2) \\ &= O((a^{(l)})^1) \\ &\leq O((a^{(l)})^{\frac{1}{2}}). \end{aligned}$$

This prove (2).

For $\forall k = 1, \dots, N$, denote by $V_1 \Sigma V_2^T$ as the SVD of $\text{unfold}_k(\mathcal{X}^{(l)} + \frac{1}{\mu^{(l)}} \mathcal{P}_k^{(l)})$ in the l^{th} iteration. Based on the updating equation in Algorithm 1, we have

$$\mathcal{M}_k^{(l)} = \text{fold}_k \left(V_1 \Lambda_k V_2^T \right),$$

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where $\Lambda = \text{diag}(D_{a_k, \varepsilon}(\sigma_1), \dots, D_{a_k, \varepsilon}(\sigma_n))$, σ_i is the i^{th} diagonal element of Σ and

$$a_k = \left(\frac{\lambda}{\mu} \prod_{j \neq k} P_{ls}^* \left(M_{j(j)^{(l)}} \right) \right) = O\left(\left(\mu^{(l)}\right)^{-1}\right), \quad (4)$$

where $\mu^{(l)} \rightarrow \infty$. Thus, combining the multiplier updating rule of ADMM and (2), we can obtain:

$$\begin{aligned} \|\mathcal{P}_k^{(l+1)}\|_F &= \|\mathcal{P}_k^{(l)} + \mu^{(l)}(\mathcal{X}^{(l)} - \mathcal{M}_k^{(l)})\|_F \\ &= \mu^{(l)} \|V_1(\Sigma - \Lambda)V_2^T\|_F \\ &= \mu^{(l)} \|\text{diag}(\sigma_1 - D_{a_k, \varepsilon}(\sigma_1), \dots, \sigma_n - D_{a_k, \varepsilon}(\sigma_n))\|_F \\ &\leq \mu^{(l)} O((a_k)^{\frac{1}{2}}) \\ &= O\left(\left(\mu^{(l)}\right)^{\frac{1}{2}}\right). \end{aligned} \quad (5)$$

By using (5), we can obtain

$$\begin{aligned} \|\mathcal{X}^{(l)} - \mathcal{M}_k^{(l)}\|_F &= \frac{1}{\mu^{(l)}} \|\mathcal{P}_k^{(l+1)} - \mathcal{P}_k^{(l)}\|_F \\ &\leq \frac{1}{\mu^{(l)}} \left(\|\mathcal{P}_k^{(l+1)}\|_F + \|\mathcal{P}_k^{(l)}\|_F \right) \\ &= O\left(\left(\mu^{(l)}\right)^{-\frac{1}{2}}\right). \end{aligned} \quad (6)$$

This proves the first term in (1) in Theorem 3.

Denote $\mathcal{O}^{(l)} = \frac{\beta \mathcal{Y} + \sum_j (\mu^{(l)} \mathcal{M}_j^{(l)} - \mathcal{P}_j^{(l)})}{\beta + N\mu^{(l)}}$, and then we have

$$\begin{aligned} \|\mathcal{O}^{(l)} - \mathcal{X}^{(l)}\|_F &= \left\| \frac{\beta \mathcal{Y} + \sum_j (\mu^{(l)} \mathcal{M}_j^{(l)} - \mathcal{P}_j^{(l)})}{\beta + N\mu^{(l)}} - \mathcal{X}^{(l)} \right\|_F \\ &= \left\| \frac{\beta(\mathcal{Y} - \mathcal{X}^{(l)})}{\beta + N\mu^{(l)}} \right\|_F + \left\| \frac{\sum_j (\mu^{(l)} (\mathcal{M}_j^{(l)} - \mathcal{X}^{(l)}) - \mathcal{P}_j^{(l)})}{\beta + N\mu^{(l)}} \right\|_F \\ &\leq O\left(\left(\mu^{(l)}\right)^{-1}\right) + \frac{1}{\beta + N\mu^{(l)}} \sum_j \|\mathcal{P}_j^{(l+1)}\|_F \\ &\leq O\left(\left(\mu^{(l)}\right)^{-\frac{1}{2}}\right). \end{aligned} \quad (7)$$

Denote $\mathcal{Q} = \mathcal{O}^{(l)} \times_1 U_1^{(l)T}, \dots, \times_N U_N^{(l)T}$, $b^{(l)} = \frac{1}{\beta + N\mu^{(l)}}$, and we have

$$\begin{aligned} & \left\| \mathcal{S}^{(l+1)} \times_1 U_1^{(l)}, \dots, \times_N U_N^{(l)} - \mathcal{O}^{(l)} \right\|_F = \left\| \mathcal{S}^{(l+1)} - \mathcal{Q} \right\|_F \\ & = \left(\sum_{i_1, \dots, i_N} (q_{i_1, \dots, i_N} - D_{b^{(l)}, \varepsilon}(q_{i_1, \dots, i_N}))^2 \right)^{\frac{1}{2}} \\ & \leq \left(\sum_{i_1, \dots, i_N} (O((\mu^{(l)})^{-\frac{1}{2}}))^2 \right)^{\frac{1}{2}} \\ & = O\left(\left(\mu^{(l)}\right)^{-\frac{1}{2}}\right). \end{aligned} \quad (8)$$

$\forall n = 1, \dots, N$, update $U_n^{(l+1)}$ by solving

$$\min_U \left\| \mathcal{S} \times_1 U_1^{(l+1)}, \dots, U_{n-1}^{(l+1)} \times_n U \times_{n+1} U_{n+1}^{(l)}, \dots, U_N^{(l)} - \mathcal{O} \right\|_F^2,$$

and then

$$\begin{aligned} & \left\| \mathcal{X}^{(l+1)} - \mathcal{O}^{(l)} \right\|_F \\ & = \left\| \mathcal{S}^{(l+1)} \times_1 U_1^{(l+1)}, \dots, \times_N U_N^{(l+1)} - \mathcal{O}^{(l)} \right\|_F \\ & \leq \left\| \mathcal{S}^{(l+1)} \times_1 U_1^{(l)}, \dots, \times_N U_N^{(l)} - \mathcal{O}^{(l)} \right\|_F \\ & \leq O\left(\left(\mu^{(l)}\right)^{-\frac{1}{2}}\right). \end{aligned} \quad (9)$$

Based on (7) and (9), we can obtain

$$\begin{aligned} \left\| \mathcal{X}^{(l+1)} - \mathcal{X}^{(l)} \right\|_F & \leq \left\| \mathcal{X}^{(l+1)} - \mathcal{O}^{(l)} \right\|_F + \left\| \mathcal{O}^{(l)} - \mathcal{X}^{(l)} \right\|_F \\ & = O\left(\left(\mu^{(l)}\right)^{-\frac{1}{2}}\right). \end{aligned}$$

This proves the second term (1) in Theorem 3. ■

2 PARAMETER SETTING DETAILS

2.1 Discussion on β setting

In our experiments we set $\beta = cv^{-1}$, and in this section, we will provide clarifications on this parameter setting strategy. Let's first consider the following matrix-based proximal problem:

$$\hat{X} = \arg \min_{X \in \mathbb{R}^{m \times n}} \frac{1}{\beta} \log(|d_i| + \varepsilon) + \frac{1}{2} \|X - Y\|_F^2, \quad (10)$$

where d_i is the i -th singular value of X . Based Theorem 2, we can define $\hat{X} = U\hat{D}V^T$ as the SVD of \hat{X} , and $Y = U\Sigma V^T$ as the SVD of Y , where $\hat{D} = \text{diag}(\hat{d}_1, \hat{d}_2, \dots, \hat{d}_n)$ and $\Sigma = \text{diag}(\sigma_1, \sigma_2, \dots, \sigma_n)$. Approximately let $\varepsilon = 0$, and then we have

$$\begin{aligned} \langle \hat{X}, Y - \hat{X} \rangle & = \text{Tr}(\hat{X}^T(Y - \hat{X})) \\ & = \text{Tr}\left(\left(U\hat{D}V^T\right)^T U(\Sigma - \hat{D})V^T\right) = \sum_{i=1}^r \hat{d}_i(\sigma_i - \hat{d}_i) \\ & = \sum_{i=1}^r \left(\frac{\sigma_i + \sqrt{\sigma_i^2 - 4\beta^{-1}}}{2}\right) \left(\frac{\sigma_i - \sqrt{\sigma_i^2 - 4\beta^{-1}}}{2}\right) \\ & = \sum_{i=1}^r \frac{\sigma_i^2 - (\sigma_i^2 - 4\beta^{-1})}{4} = r\beta^{-1}. \end{aligned}$$

Thus, we can obtain $\beta = \frac{r}{\langle \hat{X}, Y - \hat{X} \rangle}$. Since $\frac{\langle \hat{X}, Y - \hat{X} \rangle}{mn}$ is with the same order of magnitude as

$E\{\hat{X}\}E\{Y - \hat{X}\} = E\{Y\}E\{Y - \hat{X}\} \approx E\{Y\}E\{Y - X\}$, where X define the groundtruth, and $E\{A\}$ define the mean value of all elements in a matrix A . Since $E\{Y - X\}$ is with the same order of magnitude as $v = \sqrt{E\{Y - X\}^2}$, we have $\beta \approx \hat{c} \frac{r}{mnE\{Y\}} v^{-1}$. This derivation can be easily generalized to tensor case in a similar fashion, and thus we can use $\beta = cv^{-1}$ to set β .