## UNIQUENESS IN INVERSE SCATTERING PROBLEMS WITH PHASELESS FAR-FIELD DATA AT A FIXED FREQUENCY\*

XIAOXU XU<sup>†</sup>, BO ZHANG<sup>‡</sup>, AND HAIWEN ZHANG<sup>§</sup>

Abstract. This paper is concerned with uniqueness in inverse acoustic scattering with phaseless far-field data at a fixed frequency. The main difficulty of this problem is the so-called translation invariance property of the modulus of the far-field pattern generated by one plane wave as the incident field. Based on our previous work [J. Comput. Phys., 345 (2017), pp. 58–73], the translation invariance property of the phaseless far-field pattern can be broken by using infinitely many sets of superpositions of two plane waves as the incident fields at a fixed frequency. In this paper, we prove that the obstacle and the index of refraction of an inhomogeneous medium can be uniquely determined by the phaseless far-field patterns generated by infinitely many sets of superpositions of two plane waves at a fixed frequency under the condition that the obstacle is a priori known to be a sound-soft or nonabsorbing impedance obstacle and the index of refraction n of the inhomogeneous medium is real-valued and satisfies that either  $n - 1 \ge c_1$  or  $n - 1 \le -c_1$  in the support of n - 1 for some positive constant  $c_1$ . To the best of our knowledge, this is the first uniqueness result in inverse scattering with phaseless far-field operators, which is also established in this paper by using a factorization of the far-field operators.

Key words. uniqueness, inverse scattering, phaseless far-field pattern, Dirichlet boundary conditions, impedance boundary conditions, inhomogeneous medium

AMS subject classifications. 78A46, 35P25

**DOI.** 10.1137/17M1149699

1. Introduction. Inverse scattering by bounded obstacles and inhomogeneous media has wide applications in many areas such as radar and sonar detection, geophysical prospection, medical imaging, and nondestructive testing (see, e.g. [11]). The present paper is concerned with inverse scattering with phaseless far-field data associated with incident plane waves.

To provide a precise description of the problem, assume that the obstacle D is an open and bounded domain in  $\mathbb{R}^3$  with  $C^2$ -boundary  $\partial D$  such that the exterior  $\mathbb{R}^3 \setminus \overline{D}$  of  $\overline{D}$  is connected. Consider the time-harmonic  $(e^{-i\omega t}$  time-dependence) plane wave

$$u^{i} = u^{i}(x, d) := \exp(ikd \cdot x),$$

which is incident on the obstacle D from the unbounded part  $\mathbb{R}^3 \setminus \overline{D}$ , where  $d \in \mathbb{S}^2$  is the incident direction with  $\mathbb{S}^2$  denoting the unit sphere in  $\mathbb{R}^3$ ,  $k = \omega/c > 0$  is the wave number, and  $\omega$  and c are the wave frequency and speed in the homogeneous medium

<sup>\*</sup>Received by the editors September 28, 2017; accepted for publication (in revised form) April 11, 2018; published electronically June 19, 2018.

http://www.siam.org/journals/siap/78-3/M114969.html

**Funding:** This work was partially supported by NNSF of China grants 91430102, 91630309, 11501558, and 11571355 and the National Center for Mathematics and Interdisciplinary Sciences, CAS.

<sup>&</sup>lt;sup>†</sup>Academy of Mathematics and Systems Science, Chinese Academy of Sciences, Beijing 100190, China, and School of Mathematical Sciences, University of Chinese Academy of Sciences, Beijing 100049, China (xuxiaoxu14@mails.ucas.ac.cn).

<sup>&</sup>lt;sup>‡</sup>LSEC and Academy of Mathematics and Systems Science, Chinese Academy of Sciences, Beijing, 100190, China, and School of Mathematical Sciences, University of Chinese Academy of Sciences, Beijing 100049, China (b.zhang@amt.ac.cn).

<sup>&</sup>lt;sup>§</sup>Academy of Mathematics and Systems Science, Chinese Academy of Sciences, Beijing 100190, China (zhanghaiwen@amss.ac.cn).

in  $\mathbb{R}^3 \setminus \overline{D}$ . Denote by  $u^s$  the scattered field. Then the total field  $u := u^i + u^s$  outside an impenetrable obstacle D satisfies the exterior boundary value problem:

(1.1a) 
$$\Delta u + k^2 u = 0 \quad \text{in } \mathbb{R}^3 \setminus \overline{D},$$

(1.1b) 
$$\mathscr{B}u = 0 \quad \text{on } \partial D,$$

(1.1c) 
$$\lim_{r \to \infty} r\left(\frac{\partial u^s}{\partial r} - iku^s\right) = 0, \quad r = |x|.$$

Here, (1.1a) is the well-known Helmholtz equation, and (1.1c) is the Sommerfeld radiation condition, which ensures the uniqueness of the scattered field  $u^s$ . The boundary condition  $\mathscr{B}$  in (1.1b) depends on the physical property of the obstacle D:

$$\begin{cases} \mathscr{B}u = u & \text{for a sound-soft obstacle,} \\ \mathscr{B}u = \partial u / \partial \nu + \eta u & \text{for an impedance obstacle,} \end{cases}$$

where  $\nu$  is the unit outward normal to the boundary  $\partial D$  and  $\eta$  is the impedance function satisfying that  $\operatorname{Im}[\eta(x)] \geq 0$  for all  $x \in \partial D$ . In this paper, we assume that  $\eta \in C(\partial D)$ , that is,  $\eta$  is continuous on  $\partial D$ . If  $\operatorname{Im}[\eta(x)] > 0$  for all  $x \in \partial D$ , we say the impedance boundary condition is *absorbing*; if  $\operatorname{Im}[\eta(x)] = 0$  for all  $x \in$  $\partial D$ , we say the impedance boundary condition is *nonabsorbing*. When  $\eta = 0$ , the impedance boundary condition becomes the Neumann boundary condition (soundhard obstacles), so the Neumann boundary condition is nonabsorbing.

The problem of scattering of a plane wave by an inhomogeneous medium is modeled by the medium scattering problem:

(1.2a) 
$$\Delta u + k^2 n(x)u = 0 \quad \text{in } \mathbb{R}^3,$$

(1.2b) 
$$\lim_{r \to \infty} r\left(\frac{\partial u^s}{\partial r} - iku^s\right) = 0, \quad r = |x|,$$

where  $u = u^i + u^s$  is the total field,  $u^s$  is the scattered field, and n in the reduced wave equation (1.2a) is the refractive index characterizing the inhomogeneous medium. In this paper, we assume that m := n - 1 has compact support  $\overline{D}$  and  $n \in L^{\infty}(D)$  with  $\operatorname{Re}[n(x)] > 0$  and  $\operatorname{Im}[n(x)] \ge 0$  for all  $x \in D$ . If  $\operatorname{Im}[n(x)] > 0$  for all  $x \in D$ , then the medium is called *absorbing*; if  $\operatorname{Im}[n(x)] = 0$  for all  $x \in D$  (so n is real-valued), then the medium is called *nonabsorbing*.

The existence of a unique (variational) solution to problems (1.1a)-(1.1c) and (1.2a)-(1.2b) has been proved in [11, 17, 18] (see Theorem 3.11 in [11] and Theorem 1.1 in [17] for the exterior Dirichlet problem, Theorem 2.2 in [17] for the exterior impedance problem, and Theorem 6.9 in [18] for the medium scattering problem (1.2a)-(1.2b)). In particular, it is well known that the scattered field  $u^s$  has the asymptotic behavior

$$u^{s}(x,d) = \frac{e^{ik|x|}}{|x|} \left\{ u^{\infty}(\hat{x},d) + O\left(\frac{1}{|x|}\right) \right\}, \quad |x| \to \infty,$$

uniformly for all observation directions  $\hat{x} = x/|x| \in \mathbb{S}^2$ , where  $u^{\infty}(\hat{x}, d)$  is the far-field pattern of  $u^s$  which is an analytic function of  $\hat{x} \in \mathbb{S}^2$  for each  $d \in \mathbb{S}^2$  and of  $d \in \mathbb{S}^2$  for each  $\hat{x} \in \mathbb{S}^2$  (see, e.g., [11]).

The inverse scattering problem is to determine the shape and location of the obstacle D and its physical property or the index of refraction n of the medium from

1738

the near-field (the scattered field  $u^s$  or the total field u) or the far-field pattern  $u^{\infty}$ . In many practical applications, the phase of the near-field or the far-field pattern cannot be measured accurately compared with its modulus or intensity. Thus, it is often desirable to recover the obstacle and the medium from the modulus or intensity of the near-field or the far-field pattern (or the phaseless near-field data or the phaseless far-field data). The inverse scattering problem with phaseless near-field data ( $|u^s|$  or |u| on a measurement surface enclosing the obstacle or the medium) or phaseless farfield pattern  $|u^{\infty}|$  is called the *inverse scattering problem with phaseless data*, while the inverse scattering problem with the near-field data (the scattered field  $u^s$  or the total field u on a measurement surface enclosing the obstacle or the medium) or the far-field pattern  $u^{\infty}$  is called the *inverse scattering problem with full data*.

Over the past three decades, inverse scattering problems with full data have been extensively studied mathematically and numerically (see, e.g., the monographs [11, 17] and the references quoted there). The inverse scattering problem with phaseless nearfield data is also called the (near-field) phase retrieval problem in optics and other physical and engineering sciences and has also been widely studied numerically over the past decades (see, e.g., [6, 7]). For example, many reconstruction algorithms have been developed to recover the obstacle or the refractive index of the medium from the phaseless near-field data (or the phaseless total near-field data), corresponding to plane wave incidence or point source incidence (see, e.g., [8, 9, 10, 25, 28, 29, 34, 36] and the references quoted there). However, few results are available for the mathematical study (such as uniqueness and stability) of the near-field phase retrieval problem. This is mainly because Rellich's lemma (see [11, Lemma 2.12])—which not only ensures uniqueness for scattering solutions but also establishes the one-to-one correspondence between the scattered fields and their far-field patterns and plays an essential role for the mathematical study of the inverse scattering problems with full data—does not work anymore for inverse scattering with phaseless data. This fact makes the phaseless inverse scattering problems much more difficult to study mathematically. Recently, a uniqueness result was established in [19] for recovering a nonnegative, smooth, compactly supported, real-valued potential from the phaseless near-field data corresponding to all incident point sources placed on a spherical surface for an interval of frequencies. This uniqueness result was extended in [20] to the case of recovering the smooth wave speed in the three-dimensional Helmholtz equation. Reconstruction procedures were introduced in [21, 32, 33] for inverse medium scattering problems with phaseless near-field data. Recently in [30], the stability analysis was established for a linearized near-field phase retrieval problem for weakly scattering objects known as the contrast transfer function model in X-ray phase contrast imaging.

In contrast to the case with phaseless near-field data, inverse scattering with phaseless far-field data is more challenging due to the *translation invariance property* of the phaseless far-field pattern which was proved in [22] for sound-soft obstacles and in [26] for sound-hard and impedance obstacles (see also [37]). For the shifted obstacle  $D_{\ell} := \{x + \ell : x \in D\}$  or the refractive index of the shifted inhomogeneous medium,  $n_{\ell}(x) := n(x - \ell)$  with  $\ell \in \mathbb{R}^3$ , the scattered field  $u_{\ell}^s$  corresponding to the incident plane wave  $u^i(x, d) = e^{ikx \cdot d}$  is given as

$$u_{\ell}^{s}(x,d) = e^{ik\ell \cdot d} u^{s}(x-\ell,d), \quad x \in \mathbb{R}^{3} \setminus \overline{D_{\ell}}, \ d \in \mathbb{S}^{2},$$

in terms of the scattered field  $u^s$  corresponding to D or n. The corresponding far-field pattern is

$$u_{\ell}^{\infty}(\hat{x},d) = e^{ik\ell \cdot (d-\hat{x})} u^{\infty}(\hat{x},d), \quad \hat{x},d \in \mathbb{S}^2, \ \ell \in \mathbb{R}^3,$$

where  $u_{\ell}^{\infty}$  is the far-field pattern for the obstacle  $D_{\ell}$  or the refractive index  $n_{\ell}$ . Thus we have the translation invariance property

(1.3) 
$$|u_{\ell}^{\infty}(\hat{x},d)| = |u^{\infty}(\hat{x},d)|, \quad \hat{x},d \in \mathbb{S}^2, \ \ell \in \mathbb{R}^3.$$

This means that it is impossible to reconstruct the location of the obstacle D or the inhomogeneous medium from the phaseless far-field pattern with one plane wave as the incident field. However, several reconstruction algorithms have been developed to reconstruct the shape of the obstacle from the phaseless far-field data with one plane wave as the incident field (see [1, 14, 15, 16, 22, 24, 35]). For plane wave incidence no uniqueness results are available for the general inverse obstacle scattering problems with phaseless far-field data. By assuming a priori the obstacle to be a sound-soft ball centered at the origin, uniqueness was established in determining the radius of the ball from a single phaseless far-field datum in [27].

We remark that a continuation algorithm was proposed in [2] to reconstruct the shape of a perfectly reflecting grating profile from the phaseless near-field data associated with incident plane waves, and a recursive linearization algorithm in frequencies was introduced in [3] to recover the shape of multiscale sound-soft large rough surfaces from phaseless measurements of the scattered field generated by tapered waves with multiple frequencies. Note that the phaseless near-field data is also invariant under translations in the nonperiodic direction of the periodic grating profile in the former case and in the vertical direction of the unbounded rough surface in the latter case.

As discussed above, for plane wave incidence it is the translation invariance property (1.3) which makes it impossible to recover the location of the scattering obstacle from phaseless far-field data. Recently in [37], it was proved that the translation invariance property of the phaseless far-field pattern can be broken if superpositions of two plane waves rather than one plane wave are used as the incident fields with an interval of frequencies. A recursive Newton-type iteration algorithm in frequencies was also developed in [37] to recover both the location and the shape of the obstacle simultaneously from multifrequency phaseless far-field data. This approach was further extended to inverse scattering by locally rough surfaces with phaseless far-field data in [38]. On the other hand, by means of the results in [37] it is also easy to see that the translation invariance property of the phaseless far-field pattern can be broken by using infinitely many sets of superpositions of two plane waves with different directions as the incident fields at a fixed frequency. Based on this, we have recently developed a fast imaging algorithm in [39] to recover scattering obstacles by phaseless (or intensity-only) far-field data at a fixed frequency.

Motivated by [37, 38, 39], we prove in this paper that the obstacle D and the refractive index n can be uniquely determined by the phaseless far-field patterns generated by infinitely many sets of superpositions of two plane waves with different directions at a fixed frequency under the condition that D is a priori known to be a sound-soft or a nonabsorbing impedance obstacle and n is a priori assumed to be real-valued with the condition that either  $n-1 \ge c_1$  or  $n-1 \le -c_1$  for some constant  $c_1 > 0$ . As far as we know, this is the first uniqueness result in inverse scattering with phaseless far-field data. Our proofs are based essentially on the limit of the normalized eigenvalues of the far-field operators (Theorem 3.9), which is established in this paper by using a factorization of the far-field operators. It should be pointed out that the limit of the normalized eigenvalues of the far-field operators is established only for sound-soft or nonabsorbing impedance obstacles and for nonabsorbing inhomogeneous media. For the absorbing cases, however, the limit of the normalized eigenvalues of the far-field operators is not yet known. On the other hand, it should be noted

1740

that we currently do not know if it is possible to detect the property of the obstacle or the inhomogeneous medium by other methods with the phaseless far-field data since all the previous methods that can detect the property of the obstacle or the inhomogeneous medium do not work for phaseless far-field data. In the near future, we hope to extend the uniqueness results to the case without a priori knowing the property of the obstacle and the inhomogeneous medium.

This paper is organized as follows. The main results are presented in section 2. Spectral properties of the far-field operators are established in section 3. Section 4 is devoted to the proof of the main results. Conclusions are given in section 5.

2. The main results. In this section, let the wave number k be arbitrarily fixed. Following [37, 39], we make use of the following superposition of two plane waves as the incident field:

$$u^{i} = u^{i}(x; d_{1}, d_{2}) = u^{i}(x, d_{1}) + u^{i}(x, d_{2}) = e^{ikx \cdot d_{1}} + e^{ikx \cdot d_{2}}$$

where  $d_1, d_2 \in \mathbb{S}^2$  are the incident directions. Then the scattered field  $u^s$  has the asymptotic behavior

$$u^{s}(x;d_{1},d_{2}) = \frac{e^{ik|x|}}{|x|} \left\{ u^{\infty}(\hat{x};d_{1},d_{2}) + O\left(\frac{1}{|x|}\right) \right\}, \quad |x| \to \infty,$$

uniformly for all observation directions  $\hat{x} \in \mathbb{S}^2$ . From the linear superposition principle it follows that

$$u^{s}(x; d_{1}, d_{2}) = u^{s}(x, d_{1}) + u^{s}(x, d_{2})$$

and

(2.1) 
$$u^{\infty}(\hat{x}; d_1, d_2) = u^{\infty}(\hat{x}, d_1) + u^{\infty}(\hat{x}, d_2),$$

where  $u^s(x, d_j)$  and  $u^{\infty}(\hat{x}, d_j)$  are the scattered field and its far-field pattern corresponding to the incident plane wave  $u^i(x, d_j)$ , j = 1, 2.

Denote by  $u_j^s$  and  $u_j^\infty$  the scattered field and its far-field pattern, respectively, associated with the obstacle  $D_j$  (or the inhomogeneous medium with the refractive index  $n_j$ ) and corresponding to the incident field  $u^i$ , j = 1, 2. Then we have the following main results on uniqueness in inverse scattering with phaseless far-field data.

THEOREM 2.1. (i) Assume that  $D_1$  and  $D_2$  are two sound-soft obstacles. If the corresponding far-field patterns satisfy that

(2.2) 
$$|u_1^{\infty}(\hat{x}; d_1, d_2)| = |u_2^{\infty}(\hat{x}; d_1, d_2)| \quad \forall \hat{x}, d_1, d_2 \in \mathbb{S}^2,$$

then  $D_1 = D_2$ .

(ii) Assume that  $D_1$  and  $D_2$  are two nonabsorbing impedance obstacles (i.e.,  $\operatorname{Im}(\eta_j) = 0, \ j = 1, 2$ ) with the impedance coefficient  $\eta_j \in C(\partial D_j), \ j = 1, 2$ . If the corresponding far-field patterns satisfy (2.2), then  $D_1 = D_2$  and  $\eta_1 = \eta_2$ .

(iii) Assume that  $n_1, n_2 \in L^{\infty}(\mathbb{R}^3)$  are the refractive indices of two nonabsorbing inhomogeneous media (i.e.,  $\operatorname{Im}(n_j) = 0$  in  $D_j$ , j = 1, 2) with  $n_j - 1$  supported in  $\overline{D_j}$ , j = 1, 2. Assume further that there is a constant  $c_1 > 0$  such that either  $n_j - 1 \ge c_1$  in  $D_j$  (j = 1, 2) or  $n_j - 1 \le -c_1$  in  $D_j$  (j = 1, 2). If the corresponding far-field patterns satisfy (2.2), then  $n_1 = n_2$ .

We need much less phaseless far-field data to determine sound-soft or nonabsorbing impedance obstacles, as seen from the following theorem. THEOREM 2.2. (i) Assume that  $D_1$  and  $D_2$  are two sound-soft obstacles. If the corresponding far-field patterns satisfy that

$$|u_1^{\infty}(\hat{x},d)| = |u_2^{\infty}(\hat{x},d)| \quad \forall \hat{x},d \in \mathbb{S}^2$$

and

$$|u_1^{\infty}(\hat{x}; d, d_0)| = |u_2^{\infty}(\hat{x}; d, d_0)| \quad \forall \hat{x}, d \in \mathbb{S}^2$$

for an arbitrarily fixed  $d_0 \in \mathbb{S}^2$ , then  $D_1 = D_2$ .

(ii) Assume that  $D_1$  and  $D_2$  are two nonabsorbing impedance obstacles (i.e.,  $\operatorname{Im}(\eta_j) = 0, \ j = 1, 2$ ) with the impedance coefficient  $\eta_j \in C(\partial D_j), \ j = 1, 2$ . If the corresponding far-field patterns satisfy (2.3) and (2.4), then  $D_1 = D_2$  and  $\eta_1 = \eta_2$ .

Remark 2.3. (i) Theorem 2.2 remains true for the two-dimensional case, and the proof is the same.

(ii) Theorem 2.1(ii) also holds in two dimensions if the assumption  $n_1, n_2 \in L^{\infty}(\mathbb{R}^3)$  is replaced by the condition that  $n_j$  is piecewise in  $W^{1,p}(D_j)$  with p > 2, j = 1, 2. In this case, the proof is similar except that we need Bukhgeim's result in [5] (see also the theorem in section 4.1 in [4]) instead of [18, Theorem 6.26] in the proof.

3. Spectrum of the far-field operators. Our proofs of the main results, Theorems 2.1 and 2.2, depend essentially on the spectral properties of the far-field operator  $F: L^2(\mathbb{S}^2) \to L^2(\mathbb{S}^2)$  defined by

(3.1) 
$$(Fg)(\hat{x}) := \int_{\mathbb{S}^2} u^{\infty}(\hat{x}, d)g(d)ds(d), \quad \hat{x} \in \mathbb{S}^2.$$

Since the kernel  $u^{\infty}(\hat{x}, d)$  is analytic in  $\hat{x} \in \mathbb{S}^2$  and in  $d \in \mathbb{S}^2$ , respectively, the farfield operator F is compact and hence has at most a countable number of eigenvalues with the only possible accumulation point being 0. Further, the multiplicity of each eigenvalue is finite since the dimension of the null space of  $\lambda I - F$  for each nonzero eigenvalue  $\lambda$  is finite. We need more spectral properties of the far-field operators.

**3.1. A countably infinite number of eigenvalues of far-field operators.** In this subsection, we will show that F has a countably infinite number of nonzero eigenvalues for the cases considered in this paper. To this end, we introduce the adjoint operator  $F^*: L^2(\mathbb{S}^2) \to L^2(\mathbb{S}^2)$  defined by

$$(Fg,h) = (g,F^*h) \quad \forall g,h \in L^2(\mathbb{S}^2),$$

where  $(\cdot, \cdot)$  is the inner product of  $L^2(\mathbb{S}^2)$ . The following lemma shows that F is normal for the cases considered in this paper, which was proved in [17] for a soundsoft or sound-hard obstacle (see [17, Theorem 1.8]) and an impedance obstacle with real-valued impedance coefficient  $\eta$  (see [17, Theorem 2.5(e)]) and in [18] for an inhomogeneous medium with real-valued index of refraction  $n \in L^{\infty}(\mathbb{R}^3)$  satisfying that n-1 has a compact support (see [18, Theorem 6.16]).

LEMMA 3.1. For a sound-soft obstacle or an impedance obstacle with real-valued impedance function  $\eta \in L^{\infty}(\partial D)$  and for an inhomogeneous medium with real-valued index of refraction  $n \in L^{\infty}(\mathbb{R}^3)$  satisfying that n-1 has a compact support, we have

(3.2) 
$$F - F^* - \frac{ik}{2\pi}F^*F = 0,$$

so F is normal.

## Copyright © by SIAM. Unauthorized reproduction of this article is prohibited.

Remark 3.2. Define the scattering operator  $\mathcal{S}: L^2(\mathbb{S}^2) \to L^2(\mathbb{S}^2)$  by

$$\mathcal{S} := I + \frac{ik}{2\pi}F.$$

Then

$$\mathcal{S}^*\mathcal{S} = \left(I - \frac{ik}{2\pi}F^*\right)\left(I + \frac{ik}{2\pi}F\right) = I.$$

Hence S is *unitary*. From the fact that the eigenvalues of a unitary operator lie on the unit circle in the complex plane, we know that every nonzero eigenvalue of F lies on the circle

(3.3) 
$$\left\{ z \in \mathbb{C} : \left| z - \frac{2\pi i}{k} \right| = \frac{2\pi}{k} \right\}$$

in the upper-half complex plane. We later show (Theorem 3.9) that the eigenvalues tend to zero from the left half of this circle (or the normalized nonzero eigenvalues tend to -1) for both sound-soft obstacles and real-valued indices of refraction n with  $n-1 \leq -c_1 < 0$  in D and from the right half of this circle (or the normalized nonzero eigenvalues tend to 1) for impedance obstacles with real-valued impedance coefficients  $\eta$  and real-valued indices of refraction n with  $n-1 \geq c_1 > 0$  in D. Our proof is based essentially on a factorization of the far-field operator in which the middle operator can be decomposed into the sum of a coercive operator and a compact part.

To obtain a factorization of the far-field operator we introduce the boundary integral operators  $S, K, K' : H^{-1/2}(\partial D) \to H^{1/2}(\partial D)$  and  $T : H^{1/2}(\partial D) \to H^{-1/2}(\partial D)$  defined by

$$\begin{split} (S\varphi)(x) &:= \int_{\partial D} \Phi_k(x, y)\varphi(y)ds(y), \quad x \in \partial D, \\ (K\varphi)(x) &:= \int_{\partial D} \frac{\partial \Phi_k(x, y)}{\partial \nu(y)}\varphi(y)ds(y), \quad x \in \partial D, \\ (K'\varphi)(x) &:= \frac{\partial}{\partial \nu} \int_{\partial D} \Phi_k(x, y)\varphi(y)ds(y), \quad x \in \partial D, \\ (T\psi)(x) &:= \frac{\partial}{\partial \nu} \int_{\partial D} \frac{\partial \Phi_k(x, y)}{\partial \nu(y)}\psi(y)ds(y), \quad x \in \partial D \end{split}$$

and the volume integral operator  $S_m: L^2(D) \to L^2(D)$  defined by

$$(S_m\phi)(x) := \frac{\phi(x)}{m(x)} - k^2 \int_D \Phi_k(x, y)\phi(y)dy, \quad x \in D,$$

where  $m(x) = n(x) - 1 \neq 0$  for all  $x \in D$ ,  $\nu(y)$  denotes the exterior unit normal vector at  $y \in \partial D$ , and  $\Phi_k$  stands for the fundamental solution of the Helmholtz equation in three dimensions given by

$$\Phi_k(x,y) = \frac{\exp(ik|x-y|)}{4\pi|x-y|}, \quad x,y \in \mathbb{R}^3, \quad x \neq y$$

The integral operators  $S, K, K': H^{-1/2}(\partial D) \to H^{1/2}(\partial D), T: H^{1/2}(\partial D) \to H^{-1/2}(\partial D),$ and  $S_m: L^2(D) \to L^2(D)$  are bounded operators (see [11, 17, 31]).

The following factorization lemma is fundamental in the proof of the main result, Theorem 2.1.

LEMMA 3.3. (a) For a sound-soft obstacle, we have the factorization

$$F = -4\pi G S^* G^*,$$

where  $G: H^{1/2}(\partial D) \to L^2(\mathbb{S}^2)$  is the data-to-pattern operator which maps the Dirichlet boundary value of the radiating solution v to the Helmholtz equation (1.1a) onto the far-field pattern  $v^{\infty}$  and is compact, one-to-one with dense range in  $L^2(\mathbb{S}^2)$ .

(b) For an impedance obstacle with boundary condition  $\partial u/\partial \nu + \eta u = 0$  on  $\partial D$ with  $\eta \in L^{\infty}(\partial D)$  and  $\operatorname{Im}(\eta) \geq 0$ , we have

(3.5) 
$$F = -4\pi G_{imp} T^*_{imp} G^*_{imp},$$

where  $G_{imp} : H^{-1/2}(\partial D) \to L^2(\mathbb{S}^2)$  is the data-to-pattern operator which maps the impedance boundary value of the radiating solution v to the Helmholtz equation (1.1a) onto the far-field pattern  $v^{\infty}$  and is compact, one-to-one with dense range in  $L^2(\mathbb{S}^2)$ , and  $T_{imp} : H^{1/2}(\partial D) \to H^{-1/2}(\partial D)$  is given by

$$T_{imp} = T + i \operatorname{Im}(\eta) I + K' \bar{\eta} + \eta K + \eta S \bar{\eta}.$$

(c) For an inhomogeneous medium with real-valued index of refraction  $n \in L^{\infty}(D)$ and m = n - 1 > 0 (or m = n - 1 < 0) in D, we have

(3.6) 
$$F = 4\pi k^2 G_m S_m^* G_m^*,$$

where  $G_m : L^2(D) \to L^2(\mathbb{S}^2)$  is the data-to-pattern operator defined by  $G_m f = v^{\infty}$ , with  $v^{\infty}$  being the far-field pattern of the radiating solution v of

$$\Delta v + k^2 n v = -mf \quad in \ \mathbb{R}^3.$$

The data-to-pattern operator  $G_m$  is injective.

*Proof.* (a) was proved in [17] as Theorem 1.15 (see also [11, Theorem 3.29]), (b) was shown in [17] as Theorem 2.6, and (c) was proved in [18] as Theorem 6.28 (see also [11, Theorem 10.12]).

To proceed further we need to collect some properties of the middle operators in the factorization of the far-field operator in Lemma 3.3.

LEMMA 3.4. Let  $S_i, T_i$  be defined similarly as S, T, respectively, with k = i, and let  $S_0: L^2(D) \to L^2(D)$  be given by

$$(S_0\varphi)(x) := \frac{\varphi(x)}{m(x)}, \quad x \in D.$$

Then the following statements are true:

(1)  $S_i$  is self-adjoint with respect to  $L^2(\partial D)$  and coercive.

(2)  $S - S_i : H^{-1/2}(\partial D) \to H^{1/2}(\partial D)$  is compact.

(3)  $-T_i$  is self-adjoint with respect to  $L^2(\partial D)$  and coercive.

(4)  $T - T_i$  is compact from  $H^{1/2}(\partial D)$  to  $H^{-1/2}(\partial D)$ .

(5)  $T - T_i + K'\bar{\eta} + \eta K + \eta S\bar{\eta} : H^{1/2}(\partial D) \to H^{-1/2}(\partial D)$  is compact.

(6)  $S_0$  is coercive for the case  $m(x) = n(x) - 1 \ge c_1$  in  $D(-S_0)$  is coercive for the

case  $m(x) = n(x) - 1 \leq -c_1$  in D) for some constant  $c_1 > 0$ .

(7)  $S_m - S_0 : L^2(D) \to L^2(D)$  is compact.

*Proof.* Statements (1) and (2) are proved in [11, 17] (see Lemma 5.37 in [11] or Lemma 1.14(c) and (d) in [17]).

Statements (3) and (4) are proved in [17] (see Theorem 1.26(e) and (f) in [17], where different notations  $N, N_i$  are used for  $T, T_i$ , respectively).

Statement (5) follows easily from (4) and the fact that S, K, K' are compact from  $H^{1/2}(\partial D)$  to  $H^{-1/2}(\partial D)$ .

Statements (6) and (7) are shown in [11, 18] for the case m = n - 1 > 0 in D (see Theorem 10.14 in [11] or Theorem 6.30 in [18]). The case m = n - 1 < 0 in D can be shown similarly.

By Lemma 3.1 the far-field operator F is normal for the cases considered in this paper, so F has a countably infinite number of eigenvalues. However, we need to prove that F has a countably infinite number of nonzero eigenvalues. To this end, we have to show that F has finite-dimensional null space.

LEMMA 3.5. For a sound-soft obstacle or an impedance obstacle with real-valued impedance function  $\eta \in L^{\infty}(\partial D)$  and for an inhomogeneous medium with real-valued index of refraction  $n \in L^{\infty}(\mathbb{R}^3)$  satisfying that n = 1 in  $\mathbb{R}^3 \setminus D$  and n > 1 (or n < 1) in D, the dimension of the null space of F is finite.

*Proof.* For the inhomogeneous medium case, the result was proved in [11] (see Theorem 8.16 in [11]).

We only give a proof for the impedance obstacle case since the proof for a soundsoft obstacle is similar. Our proof follows an idea similar to that in the proof of Lemma 2 in [23].

Note first that if Fg = 0 for  $g \in L^2(\mathbb{S}^2)$ , then the Herglotz wave function  $v_g$  defined by

$$v_g(x) = \int_{\mathbb{S}^2} e^{ikx \cdot d} g(d) ds(d), \quad x \in \mathbb{R}^3,$$

is an eigenfunction of the negative impedance-Laplacian in D corresponding to the eigenvalue  $k^2$ . Thus, and by the one-to-one correspondence between Herglotz wave functions and their kernels g (see [11, Theorem 3.19]), the finiteness of the dimension of the null space of F follows from that of the eigenspace of the negative impedance-Laplacian in D associated with the eigenvalue  $k^2$ .

We claim that the dimension of the eigenspace of the negative impedance-Laplacian in D associated with the eigenvalue  $k^2$  is equal to the dimension of the kernel space of  $T + K'\eta + \eta K + \eta S\eta$ . Now, by Lemma 3.4 we know that

$$T + K'\eta + \eta K + \eta S\eta = T_i + (T - T_i) + K'\eta + \eta K + \eta S\eta$$

is a Fredholm-type operator, so the dimension of the kernel space of  $T + K'\eta + \eta K + \eta S\eta$ is finite. Consequently, the dimension of the null space of F is finite.

In fact, if u is an eigenfunction of the negative impedance-Laplacian in D corresponding to the eigenvalue  $k^2$ , then from the Green's representation formula it follows that

$$\begin{split} u(x) &= \int_{\partial D} \left\{ \frac{\partial u}{\partial \nu}(y) \Phi_k(x,y) - u(y) \frac{\partial \Phi_k(x,y)}{\partial \nu(y)} \right\} ds(y) \\ &= -\int_{\partial D} \left( \eta(y) \Phi_k(x,y) + \frac{\partial \Phi_k(x,y)}{\partial \nu(y)} \right) u(y) ds(y), \quad x \in D. \end{split}$$

By the jump relations of the single- and double-layer potentials, we get

$$2u = u - 2 \int_{\partial D} \left( \frac{\partial \Phi_k(x, y)}{\partial \nu(y)} + \eta(y) \Phi_k(x, y) \right) u(y) ds(y), \quad x \in \partial D,$$
  
$$2 \frac{\partial u}{\partial \nu} = -\eta u - 2 \frac{\partial}{\partial \nu} \int_{\partial D} \left( \frac{\partial \Phi_k(x, y)}{\partial \nu(y)} + \eta(y) \Phi_k(x, y) \right) u(y) ds(y), \quad x \in \partial D$$

Therefore, we have

$$0 = 2\left(\frac{\partial u}{\partial \nu} + \eta u\right) = -2\left(T + K'\eta + \eta K + \eta S\eta\right)u,$$

that is, u is an element in the kernel space of  $T + K'\eta + \eta K + \eta S\eta$ . Conversely, let  $(T + K'\eta + \eta K + \eta S\eta)\varphi = 0$  for  $\varphi \in H^{1/2}(\partial D)$ . Define the combined double- and single-layer potentials:

$$u(x) := \int_{\partial D} \left( \frac{\partial \Phi_k(x, y)}{\partial \nu(y)} + \eta(y) \Phi_k(x, y) \right) \varphi(y) ds(y), \quad x \in \mathbb{R}^3 \setminus \partial D.$$

By the jump relations of the layer potentials, it is easy to show that u is an eigenfunction of the negative impedance-Laplacian in D corresponding to the eigenvalue  $k^2$ . This means that the required claim is correct. The proof is thus complete.

Combining Lemmas 3.1 and 3.5, we can establish the following theorem.

THEOREM 3.6. For a sound-soft obstacle or an impedance obstacle with realvalued impedance function  $\eta \in L^{\infty}(\partial D)$  and for an inhomogeneous medium with real-valued index of refraction  $n \in L^{\infty}(\mathbb{R}^3)$  satisfying that n = 1 in  $\mathbb{R}^3 \setminus D$  and n > 1 (or n < 1) in D, the far-field operator F has a countably infinite number of eigenvalues accumulating only at 0, and the multiplicity of each eigenvalue is finite. Furthermore, the eigenfunctions form an orthonormal basis of  $L^2(\mathbb{S}^2)$ .

Proof. From Lemma 3.1 and the spectral theorem for normal operators, we know that F has a countably infinite number of eigenvalues  $\{\lambda_n\}_{n=1}^{\infty}$  with the corresponding eigenfunctions  $\{g_n\}_{n=1}^{\infty}$  forming an orthonormal basis of  $L^2(\mathbb{S}^2)$ . We now prove that the multiplicity of each eigenvalue is finite. Suppose, to the contrary, that the multiplicity of  $\lambda_n$  is infinite for some  $n \in \mathbb{Z}$ , that is, dim $[\operatorname{Ker}(\lambda_n I - F)] = \infty$ . Then the compactness of F implies that  $\lambda_n = 0$ . But this is impossible by Lemma 3.5. From the compactness of the far-field operator F again, the unique accumulation point of the eigenvalues  $\{\lambda_n\}_{n=1}^{\infty}$  is 0. The proof is thus complete.

**3.2. Limits of the normalized eigenvalues.** Eckmann and Pillet [13] first established the limit of the normalized eigenvalues of the far-field operators for a piecewise smooth sound-soft obstacle in  $\mathbb{R}^2$  whether or not  $k^2$  is an interior Dirichlet eigenvalue of the obstacle, in the context of quantum billiards, by using a variational principle. Similar results are given in the monograph [17] for sound-soft or sound-hard obstacles in  $\mathbb{R}^3$  in order to characterize the obstacle by using the eigensystem of the far-field operator when  $k^2$  is not an eigenvalue of the underlying boundary value problem in the obstacle (see the proof of Theorem 1.23 of [17]). Similar results are also presented in [18] for inhomogeneous media with real-valued indices of refraction in  $\mathbb{R}^3$  in the case when  $k^2$  is not an eigenvalue of the underlying interior transmission problem in the support of the contrast of the inhomogeneous medium (see Lemma 6.34 of [18]). In this subsection, we extend these results to both the case of sound-soft or impedance obstacles with real-valued impedance coefficients and the case with an

1747

inhomogeneous medium with real-valued index of refraction regardless of whether or not  $k^2$  is an eigenvalue of the underlying boundary value problem in the obstacle or the underlying interior transmission problem in the support of the contrast of the inhomogeneous medium. To this end, we give the following general result on the property of the eigenvalues of a linear compact normal operator having a special factorization form.

THEOREM 3.7. Let H and X be Hilbert spaces with inner products  $(\cdot, \cdot)$ , let X<sup>\*</sup> be the dual space of X, and assume that  $F : H \to H$  is a linear compact normal operator satisfying

$$F = GM^*G^*,$$

where  $G: X \to H$  and  $M: X^* \to X$  are bounded linear operators and  $G^*: H \to X^*$ is the adjoint of G defined by

$$\langle G^*g,\varphi\rangle = (g,G\varphi) \quad \forall \varphi \in X, g \in H$$

in terms of the sesquilinear duality pairing of  $X^*$  and X. Assume further that  $G^*$  has a finite-dimensional null space and  $M = M_0 + C$  for some compact operator C and some self-adjoint operator  $M_0$  which is coercive on  $G^*(H)$  in the sense that there exists  $c_0 > 0$  such that

$$\langle \phi, M_0 \phi \rangle \ge c_0 \|\phi\|^2 \qquad \forall \phi \in G^*(H).$$

Then F has at most only a finite number of eigenvalues whose real parts are negative.

*Proof.* Suppose, to the contrary, that F has a countably infinite number of eigenvalues whose real parts are negative. By the spectral theorem for compact normal operators, there exists an infinite number of orthonormal eigenelements  $g_n \in H$  with corresponding eigenvalues  $\lambda_n, n \in \mathbb{N}$ . Then we can choose a subsequence of  $\{g_n\}_{n=1}^{\infty}$ , which we denote by  $\{g_n\}_{n=1}^{\infty}$  again, such that  $\operatorname{Re}(\lambda_n) < 0$  for all n. We may assume without loss of generality that  $G^*(g_n) \neq 0$  since the dimension of the null space of  $G^*$  is finite. Define  $f_n := G^*g_n \in X^*$ . Then

$$\operatorname{Re}(Fg_n, g_n) = \operatorname{Re}(GM^*G^*g_n, g_n) = \operatorname{Re}\langle G^*g_n, MG^*g_n \rangle$$
$$= \operatorname{Re}\langle f_n, Mf_n \rangle = \operatorname{Re}\langle f_n, M_0f_n \rangle + \operatorname{Re}\langle f_n, Cf_n \rangle.$$

Thus, and since  $\operatorname{Re}(Fg_n, g_n) = \operatorname{Re}(\lambda_n) < 0$ , we obtain that

$$|f_n||^2 \le \operatorname{Re}\langle f_n, M_0 f_n \rangle < -\operatorname{Re}\langle f_n, C f_n \rangle \le |\langle f_n, C f_n \rangle| \le ||f_n|| ||C f_n||.$$

Since  $f_n = G^* g_n \neq 0$ , it follows that

$$c_0 \|f_n\| < \|Cf_n\| \qquad \forall n \in \mathbb{N}.$$

Noting that  $(Fg_n, g_j) = \lambda_n \delta_{nj}$ , we have

$$\operatorname{Re}(F(c_ng_n + c_jg_j), c_ng_n + c_jg_j)$$
  
=  $|c_n|^2\operatorname{Re}(Fg_n, g_n) + |c_j|^2\operatorname{Re}(Fg_j, g_j) < 0$ 

where  $n \neq j$  and  $c_n, c_j \in \mathbb{C}$  are arbitrary constants satisfying that  $|c_n| + |c_j| \neq 0$ . Again, since the dimension of the null space of  $G^*$  is finite, for  $f_{n_1} := f_1 = G^*g_1$  we can choose some element from  $\{g_n\}_{n=2}^{\infty}$ , which we denote by  $g_{n_2}$ , such that

$$c_{n_1}f_{n_1} + c_{n_2}f_{n_2} = c_{n_1}G^*g_1 + c_{n_2}G^*g_{n_2} \neq 0$$

for any constants  $c_{n_1}, c_{n_2} \in \mathbb{C}$  with  $|c_{n_1}| + |c_{n_2}| \neq 0$ ; that is,  $f_{n_1}$  and  $f_{n_2}$  are linearly independent. Noting that  $\operatorname{Re}(F(c_{n_1}g_{n_1} + c_{n_2}g_{n_2}), c_{n_1}g_{n_1} + c_{n_2}g_{n_2}) < 0$ , and by the same argument as above, it follows that

$$c_0 \|c_{n_1}f_{n_1} + c_{n_2}f_{n_2}\| < \|C(c_{n_1}f_{n_1} + c_{n_2}f_{n_2})\|.$$

Repeating the above process, we can choose  $g_{n_i}$ ,  $j = 1, \ldots, N$ , such that

$$\sum_{j=1}^{N} c_{n_j} f_{n_j} \neq 0, \qquad c_0 \left\| \sum_{j=1}^{N} c_{n_j} f_{n_j} \right\| < \left\| C \sum_{j=1}^{N} c_{n_j} f_{n_j} \right\|$$

for any  $N < \infty$  and arbitrary constants  $c_{n_j} \in \mathbb{C}$ ,  $j = 1, \ldots, N$ , with  $\sum_{j=1}^{N} |c_{n_j}| \neq 0$ . Note that  $\{f_{n_j}\}_{j=1}^N = \{G^*g_{n_j}\}_{j=1}^N$  are linearly independent. Then, by the Gram–Schmidt orthonormalization process (see [12, p. 110]), there exists an orthonormal system  $\{e_{n_j}\}_{j=1}^{\infty} \subset X^*$  such that

$$\operatorname{span}\{f_{n_1},\ldots,f_{n_i}\}=\operatorname{span}\{e_{n_1},\ldots,e_{n_i}\}\quad\forall j\in\mathbb{N}$$

and

Downloaded 06/20/18 to 124.16.148.29. Redistribution subject to SIAM license or copyright; see http://www.siam.org/journals/ojsa.php

$$c_0 = c_0 \|e_{n_i}\| < \|Ce_{n_i}\|$$

Since  $e_{n_j}$  is weakly convergent to zero in  $X^*$  as  $j \to \infty$  (see [12, p. 112]), and by the compactness of C, we have

$$c_0 = c_0 ||e_{n_j}|| < ||Ce_{n_j}|| \to 0.$$

This is a contradiction. The proof is thus complete.

Making use of Theorem 3.7, in conjunction with Lemmas 3.3 and 3.4 and Theorem 3.6, we can prove the following lemma.

LEMMA 3.8. Suppose  $\{(\lambda_n, g_n)\}_{n=1}^{\infty}$  is the eigensystem of the far-field operator F such that  $\{g_n\}_{n=1}^{\infty}$  forms an orthonormal basis of  $L^2(\mathbb{S}^2)$ . Then we have the following:

(a) In the sound-soft case, there exist only finitely many eigenvalues  $\lambda_n$  satisfying that  $\operatorname{Re}(\lambda_n) > 0$ .

(b) In the nonabsorbing impedance case, there exist only finitely many eigenvalues  $\lambda_n$  satisfying that  $\operatorname{Re}(\lambda_n) < 0$ .

(c) In the nonabsorbing medium case, there exist only finitely many eigenvalues  $\lambda_n$  satisfying that

$$\operatorname{Re}(\lambda_n) \left\{ \begin{array}{ll} > 0 & \text{if } m \leq -c_1 \text{ in } D, \\ < 0 & \text{if } m \geq c_1 \text{ in } D \end{array} \right.$$

for some constant  $c_1 > 0$ .

*Proof.* We only prove (c). The proofs of (a) and (b) are similar.

We now apply Theorem 3.7 to prove (c). To do this, let  $H = L^2(\mathbb{S}^2)$ ,  $X = L^2(D)$ ,  $G = G_m$ ,  $M = 4\pi k^2 S_m$  with  $M_0 = 4\pi k^2 S_0$ , and  $C = 4\pi k^2 (S_m - S_0)$ . Then  $F = GM^*G^*$ . Now, by Lemma 3.4(6) and (7) and Lemma 3.3(c) it is known that M satisfies the assumption in Theorem 3.7 for the case  $m(x) \ge c_1$  in D. Further, by Theorem 6.30(c),  $S_m$  or, equivalently, M is an isomorphism from  $L^2(D)$  onto itself. This, together with the fact that the far-field operator F is compact and

1749

normal (by Lemma 3.1) and has finite-dimensional null space (by Lemma 3.5) and G is injective, implies that  $G^*$  has finite-dimensional null space. Thus all the assumptions in Theorem 3.7 are satisfied, and so, by Theorem 3.7, we have that the far-field operator F has at most only a finite number of eigenvalues  $\lambda_n$  with  $\operatorname{Re}(\lambda_n) < 0$ .

For the case when  $m(x) \leq -c_1$  in D,  $-F = G(-M)^*G^*$  and  $-M = -4\pi k^2 S_m$ with  $-M_0 = -4\pi k^2 S_0$  being coercive and  $-C = -4\pi k^2 (S_m - S_0)$  being compact. Thus, by Theorem 3.7, -F has at most only a finite number of eigenvalues  $-\lambda_n$  with  $-\operatorname{Re}(\lambda_n) < 0$ , or, equivalently, F has at most only a finite number of eigenvalues  $\lambda_n$  with  $\operatorname{Re}(\lambda_n) > 0$ . The proof is thus complete.

We are now in a position to state and prove the main theorem of this section.

THEOREM 3.9. Let  $\{\lambda_n\}_{n=1}^{\infty}$  be the eigenvalues of the far-field operator F. Then

$$\lim_{n \to \infty} \frac{\lambda_n}{|\lambda_n|} = \begin{cases} -1 & \text{for a sound-soft obstacle,} \\ 1 & \text{for a nonabsorbing impedance obstacle,} \\ sign(m) & \text{for a nonabsorbing medium with } |m| \ge c_1 > 0 \text{ in } D. \end{cases}$$

*Proof.* By Remark 3.2 and Theorem 3.6 we know that the possible accumulations of the normalized nonzero eigenvalues of F can only be  $\pm 1$ . Theorem 3.9 then follows easily from Theorem 3.6 and Lemma 3.8. The proof is complete.

4. Proofs of the main results. In this section we prove our main results, Theorems 2.1 and 2.2.

*Proof of Theorem* 2.1. From (2.1) it is easy to see that (2.2) is equivalent to the equation

$$(4.1) \qquad |u_1^{\infty}(\hat{x}, d_1) + u_1^{\infty}(\hat{x}, d_2)| = |u_2^{\infty}(\hat{x}, d_1) + u_2^{\infty}(\hat{x}, d_2)| \quad \forall \hat{x}, d_1, d_2 \in \mathbb{S}^2.$$

This implies that

(4.2) 
$$2\operatorname{Re}\{u_1^{\infty}(\hat{x}, d_1)\overline{u_1^{\infty}(\hat{x}, d_2)}\} = 2\operatorname{Re}\{u_2^{\infty}(\hat{x}, d_1)\overline{u_2^{\infty}(\hat{x}, d_2)}\}.$$

Define  $r_j(\hat{x}, d) := |u_j^{\infty}(\hat{x}, d)|, j = 1, 2$ . Then, by (4.1) with  $d_1 = d_2 =: d$ , we have

(4.3) 
$$r_1(\hat{x}, d) = r_2(\hat{x}, d) =: r(\hat{x}, d) \quad \forall \hat{x}, d \in \mathbb{S}^2,$$

and so

$$u_i^{\infty}(\hat{x}, d) = r(\hat{x}, d)e^{i\theta_j(\hat{x}, d)} \quad \forall \hat{x}, d \in \mathbb{S}^2, \ j = 1, 2,$$

where  $\theta_j(\hat{x}, d)$ , j = 1, 2, are real-valued functions of both variables. For the case  $r(\hat{x}, d) \equiv 0$ , we have  $u_1^{\infty}(\hat{x}, d) \equiv u_2^{\infty}(\hat{x}, d) \equiv 0$  for all  $\hat{x}, d \in \mathbb{S}^2$ .

We now consider the case  $r(\hat{x}, d) \neq 0$  for  $\hat{x}, d \in \mathbb{S}^2$ . Define

$$U := \{ (\hat{x}, d) \in \mathbb{S}^2 \times \mathbb{S}^2 | r(\hat{x}, d) \neq 0 \}.$$

Then, by the continuity of  $r(\hat{x}, d)$  in  $(\hat{x}, d) \in \mathbb{S}^2 \times \mathbb{S}^2$ , it follows that U is an open domain of  $\mathbb{S}^2 \times \mathbb{S}^2$ . Further, since  $u_j^{\infty}(\hat{x}, d)$ , j = 1, 2, are analytic functions of  $\hat{x} \in \mathbb{S}^2$ and  $d \in \mathbb{S}^2$ , respectively, we may choose two open and connected sets  $U_1, U_2 \subset \mathbb{S}^2$ small enough so that  $U_1 \times U_2 \subset U$  and  $\theta_j(\hat{x}, d)$ , j = 1, 2, are analytic with respect to  $\hat{x} \in U_1$  and  $d \in U_2$ , respectively.

Now, by (4.2) and the definition of U we have

(4.4) 
$$\cos[\theta_1(\hat{x}, d_1) - \theta_1(\hat{x}, d_2)] = \cos[\theta_2(\hat{x}, d_1) - \theta_2(\hat{x}, d_2)]$$

for all  $(\hat{x}, d_j) \in U_1 \times U_2$ , j = 1, 2. By (4.4) and the fact that  $\theta_j(\hat{x}, d)$ , j = 1, 2, are real-valued analytic functions of  $\hat{x} \in U_1$  and  $d \in U_2$ , respectively, we obtain that there holds either

(4.5) 
$$\theta_1(\hat{x}, d_1) - \theta_1(\hat{x}, d_2) = \theta_2(\hat{x}, d_1) - \theta_2(\hat{x}, d_2) \ \forall (\hat{x}, d_j) \in U_1 \times U_2$$

or

1750

(4.6) 
$$\theta_1(\hat{x}, d_1) - \theta_1(\hat{x}, d_2) = -[\theta_2(\hat{x}, d_1) - \theta_2(\hat{x}, d_2)] \ \forall (\hat{x}, d_j) \in U_1 \times U_2,$$

where j = 1, 2.

For the case when (4.5) holds, we have

$$\theta_1(\hat{x}, d_1) - \theta_2(\hat{x}, d_1) = \theta_1(\hat{x}, d_2) - \theta_2(\hat{x}, d_2) \quad \forall (\hat{x}, d_j) \in U_1 \times U_2, \ \ j = 1, 2$$

Fix  $d_2 \in U_2$  and define

$$\alpha(\hat{x}) := \theta_1(\hat{x}, d_2) - \theta_2(\hat{x}, d_2) \quad \forall \hat{x} \in U_1.$$

Then by (4.5) we have

$$u_1^{\infty}(\hat{x}, d) = r(\hat{x}, d)e^{i\theta_1(\hat{x}, d)} = r(\hat{x}, d)e^{i\alpha(\hat{x}) + i\theta_2(\hat{x}, d)} = e^{i\alpha(\hat{x})}u_2^{\infty}(\hat{x}, d)$$

for all  $(\hat{x}, d) \in U_1 \times U_2$ , where we use d to replace  $d_1$ . By the analyticity of  $u_1^{\infty}(\hat{x}, d) - e^{i\alpha(\hat{x})}u_2^{\infty}(\hat{x}, d)$  in  $d \in \mathbb{S}^2$ , we get

(4.7) 
$$u_1^{\infty}(\hat{x}, d) = e^{i\alpha(\hat{x})}u_2^{\infty}(\hat{x}, d) \quad \forall \hat{x} \in U_1, d \in \mathbb{S}^2.$$

Changing the variables  $\hat{x} \to -d$  and  $d \to -\hat{x}$  in (4.7) gives

$$u_1^{\infty}(-d, -\hat{x}) = e^{i\alpha(-d)}u_2^{\infty}(-d, -\hat{x}) \quad \forall -d \in U_1, \hat{x} \in \mathbb{S}^2.$$

The reciprocity relation  $u_j^{\infty}(\hat{x}, d) = u_j^{\infty}(-d, -\hat{x})$  for all  $\hat{x}, d \in \mathbb{S}^2$  (j = 1, 2) leads to the result

(4.8) 
$$e^{i\alpha(\hat{x})}u_2^{\infty}(\hat{x},d) = e^{i\alpha(-d)}u_2^{\infty}(\hat{x},d) \quad \forall \hat{x}, -d \in U_1.$$

Since  $r(\hat{x}, d) \neq 0$  for  $\hat{x}, d \in \mathbb{S}^2$ , it follows from (4.8), the analyticity of  $\alpha(\hat{x})$  in  $\hat{x} \in U_1$ , and the analyticity of  $u_j^{\infty}(\hat{x}, d)$  (j = 1, 2) with respect to  $\hat{x} \in \mathbb{S}^2$  and  $d \in \mathbb{S}^2$ , respectively, that

$$\exp[i\alpha(\hat{x})] = \exp[i\alpha(-d)] \quad \forall \hat{x}, -d \in U_1.$$

For a fixed  $-\tilde{d} \in U_1$  take  $d = \tilde{d}$  in the above formula to give that  $\exp[i\alpha(\hat{x})] = \exp(i\alpha)$  for all  $\hat{x} \in U_1$ , where  $\alpha := \alpha(-\tilde{d})$  is a real constant. Substituting this formula into (4.7) gives

$$u_1^{\infty}(\hat{x}, d) = e^{i\alpha} u_2^{\infty}(\hat{x}, d) \quad \forall \hat{x} \in U_1, d \in \mathbb{S}^2.$$

By the analyticity of  $u_j^{\infty}(\hat{x}, d)$  (j = 1, 2) with respect to  $\hat{x} \in \mathbb{S}^2$  it follows that

(4.9) 
$$u_1^{\infty}(\hat{x}, d) = e^{i\alpha} u_2^{\infty}(\hat{x}, d) \quad \forall \hat{x}, d \in \mathbb{S}^2.$$

For the case when (4.6) holds, an argument similar to that above gives the result

(4.10) 
$$u_1^{\infty}(\hat{x}, d) = e^{i\beta} \overline{u_2^{\infty}(\hat{x}, d)} \quad \forall \hat{x}, d \in \mathbb{S}^2,$$

## Copyright © by SIAM. Unauthorized reproduction of this article is prohibited.

1751

where  $\beta$  is a real constant.

We now prove that (4.10) does not hold. In fact, suppose  $\{(\lambda_n, g_n)\}_{n=1}^{\infty}$  is the eigensystem of the far-field operator  $F_1$  corresponding to the obstacle  $D_1$  or the refraction of index  $n_1$ . Then by (4.10) we have

$$(F_2\overline{g_n})(\hat{x}) = \int_{\mathbb{S}^2} u_2^{\infty}(\hat{x}, d) \overline{g_n(d)} ds(d) = \int_{\mathbb{S}^2} e^{i\beta} \overline{u_1^{\infty}(\hat{x}, d)g_n(d)} ds(d)$$
$$= e^{i\beta} \overline{(F_1g_n)(\hat{x})} = e^{i\beta} \overline{\lambda_n} \overline{g_n(\hat{x})}.$$

Thus,  $\{(e^{i\beta}\overline{\lambda_n}, \overline{g_n})\}_{n=1}^{\infty}$  is the eigensystem of the far-field operator  $F_2$  corresponding to the obstacle  $D_2$  or the refraction of index  $n_2$ . Theorem 3.9 implies that

$$(4.11) \qquad \lim_{n \to \infty} \frac{\lambda_n}{|\lambda_n|} = \begin{cases} -1 & \text{if } D_1 \text{ is a sound-soft obstacle,} \\ 1 & \text{if } D_1 \text{ is a nonabsorbing impedance obstacle,} \\ \text{sign}(m_1) & \text{for real-valued } n_1 \text{ with } |m_1| \ge c_1 \text{ in } D_1, \end{cases}$$

$$(4.12) \quad \lim_{n \to \infty} \frac{e^{i\beta}\overline{\lambda_n}}{|e^{i\beta}\overline{\lambda_n}|} = \begin{cases} -1 & \text{if } D_2 \text{ is a sound-soft obstacle,} \\ 1 & \text{if } D_2 \text{ is a nonabsorbing impedance obstacle,} \\ \text{sign}(m_2) & \text{for real-valued } n_2 \text{ with } |m_2| \ge c_1 \text{ in } D_2, \end{cases}$$

where  $m_j = n_j - 1$  in  $D_j$ , j = 1, 2. Note that  $D_1$  and  $D_2$  are both either soundsoft obstacles or nonabsorbing impedance obstacles. Note further that  $n_1$  and  $n_2$ are both real-valued and satisfy that either  $m_j = n_j - 1 \ge c_1$  in  $D_j$  (j = 1, 2)or  $m_j = n_j - 1 \le -c_1$  in  $D_j$  (j = 1, 2), so the sign of  $m_1$  in  $D_1$  is the same as that of  $m_2$  in  $D_2$ . Therefore, from (4.11) and (4.12) it follows that  $e^{i\beta} = 1$ . Hence  $\{\overline{\lambda_n}\}_{n=1}^{\infty}$  are the eigenvalues of the far-field operator  $F_2$ . Recall that  $\{\lambda_n\}_{n=1}^{\infty}$  are the eigenvalues of the far-field operator  $F_1$ . By Remark 3.2, both nonzero elements of  $\{\lambda_n\}_{n=1}^{\infty}$  and  $\{\overline{\lambda_n}\}_{n=1}^{\infty}$  lie on the circle (3.3) in the upper-half complex plane, which is a contradiction. This means that (4.10) does not hold.

We now consider (4.9). Let  $\{(\lambda_n, g_n)\}_{n=1}^{\infty}$  be the eigensystem of the far-field operator  $F_1$  corresponding to the obstacle  $D_1$  or the refraction of index  $n_1$ . Then it follows from (4.9) that

$$(F_2g_n)(\hat{x}) = \int_{\mathbb{S}^2} u_2^{\infty}(\hat{x}, d)g_n(d)ds(d) = \int_{\mathbb{S}^2} e^{-i\alpha}u_1^{\infty}(\hat{x}, d)g_n(d)ds(d) = e^{-i\alpha}(F_1g_n)(\hat{x}) = e^{-i\alpha}\lambda_ng_n(\hat{x}).$$

Thus,  $\{(e^{-i\alpha}\lambda_n, g_n)\}_{n=1}^{\infty}$  is the eigensystem of the far-field operator  $F_2$  corresponding to the obstacle  $D_2$  or the refraction of index  $n_2$ . By Theorem 3.9, we have

$$\lim_{n \to \infty} \frac{\lambda_n}{|\lambda_n|} = \begin{cases} -1 & \text{if } D_1 \text{ is a sound-soft obstacle,} \\ 1 & \text{if } D_1 \text{ is a nonabsorbing impedance obstacle,} \\ \text{sign}(m_1) & \text{for real-valued } n_1 \text{ with } |m_1| \ge c_1 \text{ in } D_1, \\ \\ \lim_{n \to \infty} \frac{e^{-i\alpha}\lambda_n}{|e^{-i\alpha}\lambda_n|} = \begin{cases} -1 & \text{if } D_2 \text{ is a sound-soft obstacle,} \\ 1 & \text{if } D_2 \text{ is a nonabsorbing impedance obstacle,} \\ \\ \text{sign}(m_2) & \text{for real-valued } n_2 \text{ with } |m_2| \ge c_1 \text{ in } D_2. \end{cases}$$

Similarly as above, we obtain that  $e^{-i\alpha} = 1$ . Hence

(4.13) 
$$u_1^{\infty}(\hat{x}, d) = u_2^{\infty}(\hat{x}, d) \quad \forall \hat{x}, d \in \mathbb{S}^2.$$

For two sound-soft or nonabsorbing impedance obstacles  $D_1$  and  $D_2$ , by (4.13) and [11, Theorem 5.6] we have  $D_1 = D_2$  and  $\eta_1 = \eta_2$ . For two indices of refraction  $n_1$ 

and  $n_2$  satisfying the assumptions in Theorem 2.1, by (4.13) and [18, Theorem 6.26] we have  $n_1 = n_2$ . Theorem 2.1 is thus proved.

Proof of Theorem 2.2. By (2.3) and (2.4) we know that (4.1) and (4.2) still hold with  $d_1 = d$  and  $d_2 = d_0$ . Further, by (2.3), equation (4.3) holds. Then the remaining part of the proof of Theorem 2.1 works by letting  $d_1 = d$  and  $d_2 = d_0$  and noting that  $(\hat{x}, d_0) \in U$  for all  $\hat{x}$  in a small open domain of  $\mathbb{S}^2$  (since, otherwise,  $u_j^{\infty}(\hat{x}, d_0) \equiv 0$  for all  $\hat{x} \in \mathbb{S}^2$ , and so, by Rellich's lemma,  $u_j^s(x, d_0) \equiv 0$  for all  $x \in \mathbb{R}^3 \setminus \overline{D_j}$ , leading to the contradiction that  $u^i(x, d_0) \equiv 0$  or  $\partial u^i(x, d_0)/\partial \nu + \eta u^i(x, d_0) \equiv 0$  for all  $x \in \partial D_j$ , j = 1, 2). The proof is complete.

5. Conclusion. In this paper, we established uniqueness in inverse acoustic scattering with phaseless far-field patterns associated with infinitely many sets of superpositions of two plane waves with different directions at a fixed frequency for sound-soft or nonabsorbing impedance obstacles and for a nonabsorbing inhomogeneous medium with the real-valued index of refraction n satisfying that either  $n(x) - 1 \ge c_1$  or  $n(x) - 1 \le -c_1$  in the support D for some constant  $c_1 > 0$ . To the best of our knowledge, this is the first uniqueness result in inverse scattering with phaseless far-field data. As an ongoing project, we are currently trying to remove the nonabsorbing condition on the boundary impedance function  $\eta$  and the index of refraction n and to extend the results to the case of electromagnetic waves.

## REFERENCES

- H. AMMARI, Y.T. CHOW, AND J. ZOU, Phased and phaseless domain reconstructions in the inverse scattering problem via scattering coefficients, SIAM J. Appl. Math., 76 (2016), pp. 1000–1030, https://doi.org/10.1137/15M1043959.
- [2] G. BAO, P. LI, AND J. LV, Numerical solution of an inverse diffraction grating problem from phaseless data, J. Opt. Soc. Amer. A, 30 (2013), pp. 293–299.
- [3] G. BAO AND L. ZHANG, Shape reconstruction of the multi-scale rough surface from multifrequency phaseless data, Inverse Problems, 32 (2016), 085002.
- [4] E. BLASTEN, The Inverse Problem of the Schrödinger Equation in the Plane, Licentiate Thesis, University of Helsinki, 2011; preprint, https://arxiv.org/abs/1103.6200, 2011.
- [5] A.L. BUKHGEIM, Recovering a potential from Cauchy data in the two dimensional case, J. Inverse Ill-Posed Problems, 16 (2008), pp. 19–33.
- [6] E.J. CANDES, T. STROHMER, AND V. VORONINSKI, PhaseLift: Exact and stable signal recovery from magnitude measurements via convex programming, Commun. Pure Appl. Math., 66 (2013), pp. 1241–1274.
- [7] E.J. CANDES, X. LI, AND M. SOLTANOLKOTABI, Phase retrieval via Wirtinger flow: Theory and algorithms, IEEE Trans. Inform. Theory, 61 (2015), pp. 1985–2007.
- [8] S. CAORSI, A. MASSA, M. PASTORINO, AND A. RANDAZZO, Electromagnetic detection of dielectric scatterers using phaseless synthetic and real data and the memetic algorithm, IEEE Trans. Geosci. Remote Sensing, 41 (2003), pp. 2745–2753.
- Z. CHEN AND G. HUANG, A direct imaging method for electromagnetic scattering data without phase information, SIAM J. Imaging Sci., 9 (2016), pp. 1273–1297, https://doi.org/10. 1137/15M1053475.
- [10] Z. CHEN AND G. HUANG, Phaseless imaging by reverse time migration: Acoustic waves, Numer. Math. Theory Methods Appl., 10 (2017), pp. 1–21.
- D. COLTON AND R. KRESS, Inverse Acoustic and Electromagnetic Scattering Theory, 3rd ed., Springer, New York, 2013.
- [12] L. DEBNATH AND P. MIKUSINSKI, Introduction to Hilbert Spaces with Applications, 3rd ed., Elsevier, Singapore, 2005.
- [13] J.-P. ECKMANN AND C.-A. PILLET, Spectral duality for planar billiards, Comm. Math. Phys., 170 (1995), pp. 283–313.
- [14] O. IVANYSHYN, Shape reconstruction of acoustic obstacles from the modulus of the far field pattern, Inverse Probl. Imaging, 1 (2007), pp. 609–622.
- [15] O. IVANYSHYN AND R. KRESS, Identification of sound-soft 3D obstacles from phaseless data,

1752

Inverse Probl. Imaging, 4 (2010), pp. 131–149.

- [16] O. IVANYSHYN AND R. KRESS, Inverse scattering for surface impedance from phaseless far field data, J. Comput. Phys., 230 (2011), pp. 3443–3452.
- [17] A. KIRSCH AND N. GRINBERG, The Factorization Methods for Inverse Problems, Oxford University Press, Oxford, UK, 2008.
- [18] A. KIRSCH, An Introduction to the Mathematical Theory of Inverse Problems, 2nd ed., Springer, New York, 2011.
- [19] M.V. KLIBANOV, Phaseless inverse scattering problems in three dimensions, SIAM J. Appl. Math., 74 (2014), pp. 392–410, https://doi.org/10.1137/130926250.
- [20] M.V. KLIBANOV, A phaseless inverse scattering problem for the 3-D Helmholtz equation, Inverse Probl. Imaging, 11 (2017), pp. 263–276.
- [21] M.V. KLIBANOV AND V.G. ROMANOV, Reconstruction procedures for two inverse scattering problems without the phase information, SIAM J. Appl. Math., 76 (2016), pp. 178–196, https://doi.org/10.1137/15M1022367.
- [22] R. KRESS AND W. RUNDELL, Inverse obstacle scattering with modulus of the far field pattern as data, in Inverse Problems in Medical Imaging and Nondestructive Testing, Springer, Wien, 1997, pp. 75–92.
- [23] A. LECHLEITER AND S. PETERS, The inside-outside duality for inverse scattering problems with near field data, Inverse Problems, 31 (2015), 085004.
- [24] J. LI AND H. LIU, Recovering a polyhedral obstacle by a few backscattering measurements, J. Differential Equations, 259 (2015), pp. 2101–2120.
- [25] L. LI, H. ZHENG, AND F. LI, Two-dimensional contrast source inversion method with phaseless data: TM case, IEEE Trans. Geosci. Remote Sensing, 47 (2009), pp. 1719–1736.
- [26] J. LIU AND J. SEO, On stability for a translated obstacle with impedance boundary condition, Nonlinear Anal., 59 (2004), pp. 731–744.
- [27] X. LIU AND B. ZHANG, Unique determination of a sound-soft ball by the modulus of a single far field datum, J. Math. Anal. Appl., 365 (2010), pp. 619–624.
- [28] M.H. MALEKI, A.J. DEVANEY, AND A. SCHATZBERG, Tomographic reconstruction from optical scattered intensities, J. Opt. Soc. Amer. A, 9 (1992), pp. 1356–1363.
- [29] M.H. MALEKI AND A.J. DEVANEY, Phase-retrieval and intensity-only reconstruction algorithms for optical diffraction tomography, J. Opt. Soc. Amer. A, 10 (1993), pp. 1086–1092.
- [30] S. MARETZKE AND T. HOHAGE, Stability estimates for linearized near-field phase retrieval in X-ray phase contrast imaging, SIAM J. Appl. Math., 77 (2017), pp. 384–408, https: //doi.org/10.1137/16M1086170.
- [31] W. MCLEAN, Strongly Elliptic Systems and Boundary Integral Equations, Cambridge University Press, Cambridge, UK, 2000.
- [32] R.G. NOVIKOV, Formulas for phase recovering from phaseless scattering data at fixed frequency, Bull. Sci. Math., 139 (2015), pp. 923–936.
- [33] R.G. NOVIKOV, Explicit formulas and global uniqueness for phaseless inverse scattering in multidimensions, J. Geom. Anal., 26 (2016), pp. 346–359.
- [34] L. PAN, Y. ZHONG, X. CHEN, AND S.P. YEO, Subspace-based optimization method for inverse scattering problems utilizing phaseless data, IEEE Trans. Geosci. Remote Sensing, 49 (2011), pp. 981–987.
- [35] J. SHIN, Inverse obstacle backscattering problems with phaseless data, European J. Appl. Math., 27 (2016), pp. 111–130.
- [36] T. TAKENAKA, D.J.N. WALL, H. HARADA, AND M. TANAKA, Reconstruction algorithm of the refractive index of a cylindrical object from the intensity measurements of the total field, Microwave Opt. Tech. Lett., 14 (1997), pp. 139–197.
- [37] B. ZHANG AND H. ZHANG, Recovering scattering obstacles by multi-frequency phaseless far-field data, J. Comput. Phys., 345 (2017), pp. 58–73.
- [38] B. ZHANG AND H. ZHANG, Imaging of locally rough surfaces from intensity-only far-field or near-field data, Inverse Problems, 33 (2017), 055001.
- [39] B. ZHANG AND H. ZHANG, Fast Imaging of Scattering Obstacles from Phaseless Far-Field Measurements at a Fixed Frequency, preprint, https://arxiv.org/abs/1805.09046, 2018.

Copyright © by SIAM. Unauthorized reproduction of this article is prohibited.