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### 附录A. EQ2. 15到EQ2. 16的推导 (1)


梯度定义: 设  $\mathbf{x} = (x_1, x_2, \dots, x_N)$ ,  $y = f(\mathbf{x})$  则

$$\nabla_{\mathbf{x}} y = \nabla_{\mathbf{x}} f(\mathbf{x}) = \left( \frac{\partial f(\mathbf{x})}{\partial x_1}, \frac{\partial f(\mathbf{x})}{\partial x_2}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_N} \right)$$


由此, 对第三项, 有  $\mathbf{P}\mathbf{w}^T = \sum_{i=0}^{N-1} p_i w_i$

$$\nabla_{\mathbf{w}} (\mathbf{P}\mathbf{w}^T) = \left( \frac{\partial \sum_{i=0}^{N-1} p_i w_i}{\partial w_0}, \frac{\partial \sum_{i=0}^{N-1} p_i w_i}{\partial w_1}, \dots, \frac{\partial \sum_{i=0}^{N-1} p_i w_i}{\partial w_{N-1}} \right)$$

$$= (p_0, p_1, \dots, p_{N-1}) = \mathbf{P}$$



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### 附录A. EQ2. 15到EQ2. 16的推导 (2)

对第二项, 有  $\mathbf{w}\mathbf{R}\mathbf{w}^T = \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} w_i r_{ij} w_j$ , 以对  $w_0$  的求导为例:


$$\begin{cases} a. i=0, j \neq 0 \text{ 时} & \sum_{j=1}^{N-1} r_{0j} w_j \\ b. i \neq 0, j=0 \text{ 时} & \sum_{i=1}^{N-1} r_{i0} w_i \\ c. i=0, j=0 \text{ 时} & 2w_0 r_{00} \\ d. i \neq 0, j \neq 0 \text{ 时} & 0 \end{cases}$$

注意到  $\mathbf{R}$  的对称性, 若  $i=j$ , 则  $r_{i0} = r_{0i}$ 。所以,

$$a + b + c + d = 2 \sum_{i=0}^{N-1} r_{i0} w_i = 2\mathbf{w}\mathbf{R}(:,0)$$

$\therefore \nabla_{\mathbf{w}} \mathbf{w}\mathbf{R}\mathbf{w}^T = [2\mathbf{w}\mathbf{R}(:,0), 2\mathbf{w}\mathbf{R}(:,1), \dots, 2\mathbf{w}\mathbf{R}(:,N-1)] = 2\mathbf{w}\mathbf{R}$  

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### 附录B. 误差曲线是抛物线的说明

已知  $y = \sum_{i=0}^{N-1} w_i x_i$ ,  $E[\varepsilon^2] = E[(d - y)^2]$


考察  $w_l$  的改变对  $E[\varepsilon^2]$  的影响:

$$y = \sum_{i=0}^{N-1} w_i x_i = w_l x_l + \sum_{\substack{i=0 \\ i \neq l}}^{N-1} w_i x_i = w_l x_l + C$$


所以  $E[\varepsilon^2] = E[(d - y)^2] = E[(d - w_l x_l - C)^2]$

$$= E[x_l^2] w_l^2 - E[2(d - C)x_l] w_l + E[(d - C)^2]$$

即  $E[\varepsilon^2]$  是关于  $w_l$  的一元二次方程。



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### 附录C. 对复合全微分的说明

设  $z$  是  $y_i, i=1, \dots, N$  的函数, 而  $y_i$  又是  $x$  的函数, 即

$$z = f_0(y_1, y_2, \dots, y_N), \quad y_i = f_i(x), i=1, 2, \dots, N$$


则,  $z$  对  $x$  的导数为

$$\begin{aligned} \frac{dz}{dx} &= \frac{\partial z}{\partial y_1} \frac{\partial y_1}{\partial x} + \frac{\partial z}{\partial y_2} \frac{\partial y_2}{\partial x} + \dots + \frac{\partial z}{\partial y_N} \frac{\partial y_N}{\partial x} \\ &= \sum_{i=1}^N \frac{\partial z}{\partial y_i} \frac{\partial y_i}{\partial x} \end{aligned}$$



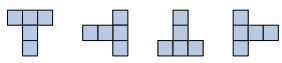
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## TC辨识网络

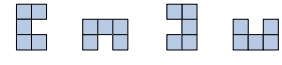


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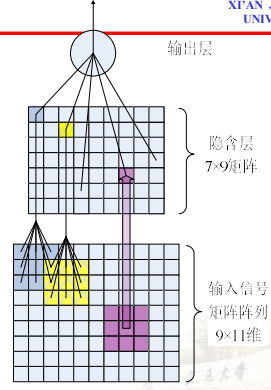
输入4种T图形



输入4种C图形



输出层



隐层  
7\*9矩阵


输入信号  
矩阵阵列  
9\*11维

解决T-C辨识的神经网络

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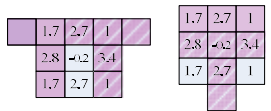
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## TC辨识结果

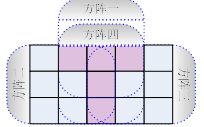


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T图形对应隐层四个神经元输出

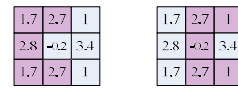


辨识T图形的四个关键方阵

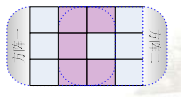


**辨识错误的图形有8种 辨识正确率为98.4%**

C图形对应隐层两个神经元输出




辨识C图形的两个关键方阵



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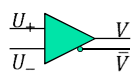
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## 理想运算放大器



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- 差模电压增益  $K_d = \infty$
- 差模输入电阻  $r_d = \infty$
- 输出电阻  $r_o = \infty$
- 带宽  $\Delta f = \infty$



- 输入电流  $I_i = 0$


$$I_i = \frac{U_+ - U_-}{r_d} = 0$$

- $U_+ = U_-$

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## 反向加法器



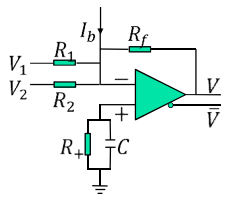
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$$\frac{V_1 - U_-}{R_1} + \frac{V_2 - U_-}{R_2} + I_b = \frac{U_- - V}{R_f}$$

$$U_+ = U_-$$

$$\frac{V_1}{R_1} + \frac{V_2}{R_2} + I_b = -\frac{V}{R_f}$$

$$w_1 x_1 + w_2 x_2 - \theta$$



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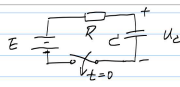
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## 微分方程的稳定状态

Hopfield 迭代解微分方程.

1. 由回路电压方程

$$RC \frac{du_c}{dt} + u_c = E$$



解方程  $u_c = E + A \cdot e^{-\frac{t}{RC}}$

A 与初始条件有关。当  $u_c(0)=0$  时  $A = -E$ 。

$t \rightarrow \infty$  时  $u_c = E$

2. 三要素法  $f(\infty) + [f(t_0) - f(\infty)]e^{-\frac{t-t_0}{\tau}}$

## 用计算机迭代解微分方程

3. 迭代  $\frac{du_c}{dt} = \frac{E - u_c}{RC}$   
 $RC = \tau$  为电路时间常数

$$\frac{u_c(t+\Delta t) - u_c(t)}{\Delta t} = \frac{E - u_c(t)}{\tau}$$

$$\Rightarrow u_c(t+\Delta t) = \frac{\Delta t E + (\tau - \Delta t) u_c(t)}{\tau}$$

## 附录A. EQ3. 28的推导

$$E = \frac{1}{2} \left( x - \sum_{i=0}^3 2^i V_i \right)^2 - \frac{1}{2} \sum_{i=0}^3 2^{2i} V_i (V_i - 1)$$

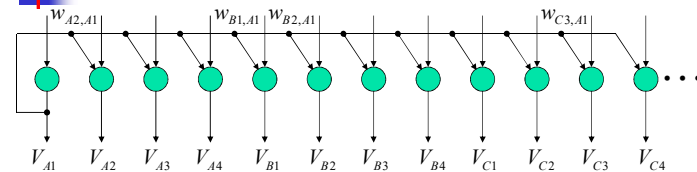
$$= \frac{1}{2} x^2 - x \sum_{i=0}^3 2^i V_i + \frac{1}{2} \left( \sum_{i=0}^3 2^i V_i \right)^2 - \frac{1}{2} \sum_{i=0}^3 2^{2i} V_i^2 + \frac{1}{2} \sum_{i=0}^3 2^{2i} V_i$$

$$= -\sum_{i=0}^3 (2^i x - 2^{2i-1}) V_i + \frac{1}{2} \left( \sum_{i=0}^3 2^i V_i \right) \left( \sum_{j=0}^3 2^j V_j \right) - \frac{1}{2} \sum_{i=0}^3 2^{2i} V_i^2$$

$$= \frac{1}{2} \sum_{j=0}^3 \sum_{i=0, i \neq j}^3 2^{(i+j)} V_i V_j - \sum_{i=0}^3 (2^i x - 2^{2i-1}) V_i$$

Return

## 附录B. 对TSP双下标的说明



$$w_{Xi,Yj} = -\alpha \delta_{XY} (1 - \delta_{ij}) - \beta \delta_{ij} (1 - \delta_{XY}) - \gamma - \lambda d_{XY} (\delta_{j,i+1} + \delta_{j,i-1})$$

$$w_{A2,A1} = -\alpha - \gamma$$

$$w_{B1,A1} = -\beta - \gamma$$

$$w_{B2,A1} = -\gamma - \lambda d_{AB}$$

$$w_{C3,A1} = -\gamma$$

Return

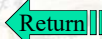
### 附录C. 对自联想记忆的说明

假设现在输入的是标准样本  $\mathbf{X}_0$ , 那么

$$\begin{aligned} \mathbf{Y} &= \text{sgn}(\mathbf{W}\mathbf{X}_0) \\ &= \text{sgn}\left[\left(\sum_{s=0}^{M-1} \mathbf{X}_s \mathbf{X}_s^T - \mathbf{I}\right)\mathbf{X}_0\right] \\ &= \text{sgn}\left[\sum_{s=0}^{M-1} \mathbf{X}_s \mathbf{X}_s^T \mathbf{X}_0 - M\mathbf{X}_0\right] \\ &= \text{sgn}\left[\mathbf{X}_0 \mathbf{X}_0^T \mathbf{X}_0 + \sum_{s=1}^{M-1} \mathbf{X}_s \mathbf{X}_s^T \mathbf{X}_0 - M\mathbf{X}_0\right] \\ &= \text{sgn}\left[120\mathbf{X}_0 + \sum_{s=1}^7 \mathbf{X}_s \mathbf{X}_s^T \mathbf{X}_0 - 8\mathbf{X}_0\right] \\ &= \text{sgn}\left[112\mathbf{X}_0 + \sum_{s=1}^7 \mathbf{X}_s \mathbf{X}_s^T \mathbf{X}_0\right] \end{aligned}$$

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### 附录D. 对双向联想记忆能量变化的说明

设从  $t$  时刻到  $t+1$  时刻, 系统由  $\mathbf{B}$  联想  $\mathbf{A}$ , 则

$$\begin{aligned} E(t) &= -\mathbf{A}^T(t)\mathbf{W}\mathbf{B}(t) + \mathbf{A}^T(t)\boldsymbol{\theta} + \mathbf{B}^T(t)\boldsymbol{\mu} \\ E(t+1) &= -\mathbf{A}^T(t+1)\mathbf{W}\mathbf{B}(t+1) + \mathbf{A}^T(t+1)\boldsymbol{\theta} + \mathbf{B}^T(t+1)\boldsymbol{\mu} \end{aligned}$$

已知  $\mathbf{B}(t+1) = \mathbf{B}(t)$ , 令  $\Delta\mathbf{A} = \mathbf{A}(t+1) - \mathbf{A}(t)$  可得:

$$\begin{aligned} \Delta E &= E(t+1) - E(t) \\ &= -[\mathbf{A}^T(t+1) - \mathbf{A}^T(t)]\mathbf{W}\mathbf{B} + [\mathbf{A}^T(t+1) - \mathbf{A}^T(t)]\boldsymbol{\theta} \\ &= -\Delta\mathbf{A}^T\mathbf{W}\mathbf{B} + \Delta\mathbf{A}^T\boldsymbol{\theta} \end{aligned}$$

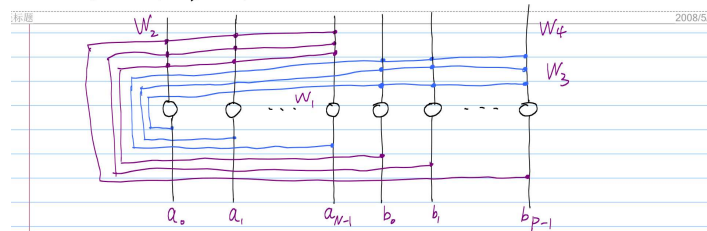
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### BAM的能量函数

BAM 能量函数



Hopfield 能量函数  $E = -\frac{1}{2}\mathbf{V}^T\mathbf{W}\mathbf{V} - \mathbf{V}^T\mathbf{I}$

其中  $\mathbf{V} = [a_0, a_1, \dots, a_{N-1}, b_0, b_1, \dots, b_{P-1}]^T = [\mathbf{A}^T \ \mathbf{B}^T]^T$

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### BAM的能量函数


BAM中:  $E = -\frac{1}{2} \begin{bmatrix} \mathbf{A} \\ \mathbf{B} \end{bmatrix}^T \bar{\mathbf{W}} \begin{bmatrix} \mathbf{A} \\ \mathbf{B} \end{bmatrix} - \begin{bmatrix} \mathbf{A} \\ \mathbf{B} \end{bmatrix}^T \cdot \underbrace{[\theta_0 \dots \theta_{N-1}]}_{\boldsymbol{\theta}^T} \underbrace{[\mu_0 \dots \mu_{P-1}]}_{\boldsymbol{\mu}^T}$

将  $\bar{\mathbf{W}}$  分块:  $\bar{\mathbf{W}} = \begin{bmatrix} \mathbf{W}_1 & \mathbf{W}_2 \\ \mathbf{W}_3 & \mathbf{W}_4 \end{bmatrix}$   $(N+P) \times (N+P)$

- 其中:  $\mathbf{W}_1 = \mathbf{0}_{N \times N}$      $\mathbf{A}$  向量元素之间的反馈,
- $\mathbf{W}_2 = \mathbf{W}$      $\mathbf{B}$  向量对  $\mathbf{A}$  向量的反馈
- $\mathbf{W}_3 = \mathbf{W}^T$      $\mathbf{A}$  对  $\mathbf{B}$  向量的反馈
- $\mathbf{W}_4 = \mathbf{0}_{P \times P}$      $\mathbf{B}$  向量元素之间的反馈.

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## BAM的能量函数

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$$\begin{aligned}
 \therefore E &= -\frac{1}{2} \begin{bmatrix} A^T & B^T \\ W^T & D \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} - A^T \vec{\theta} - B^T \vec{\mu} \\
 &= -\frac{1}{2} \begin{bmatrix} B^T W^T & A^T W \\ (1 \times N) & (1 \times P) \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} - A^T \vec{\theta} - B^T \vec{\mu} \\
 &= -\frac{1}{2} [B^T W^T A + A^T W B] - A^T \vec{\theta} - B^T \vec{\mu} \\
 &= -A^T W B - A^T \vec{\theta} - B^T \vec{\mu} \quad \text{[证完]}
 \end{aligned}$$

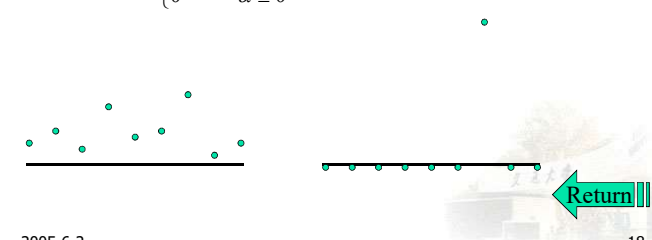
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## 附录A. MAXNET算法的解释(1)

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$$y_j(t+1) = f_i \left( y_j(t) - \varepsilon \sum_{k=1}^M y_k(t) \right) \quad j=1, 2, \dots, M$$

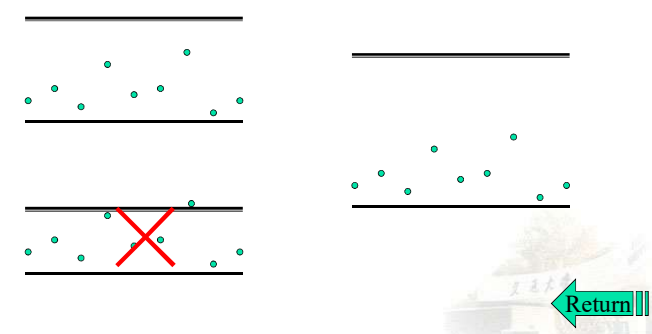
$$f_i(\alpha) = \begin{cases} C\alpha & \alpha > 0 \\ 0 & \alpha \leq 0 \end{cases} \quad C \geq 1$$


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## 附录A. MAXNET算法的解释(2)

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## ART基本原理示意流程图

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```

    graph TD
      Start([开始]) --> Input[输入任一模式]
      Input --> BottomUp[由底向上]
      BottomUp --> Maxnet[MAXNET]
      Maxnet --> TopDown[自顶向下验证]
      TopDown --> Verify{通过验证}
      Verify -- Y --> Update[更新权值]
      Update --> Input
      Verify -- N --> AllFail{已有类别均未通过}
      AllFail -- N --> Suppress[抑制未通过类别]
      Suppress --> BottomUp
      AllFail -- Y --> CanAdd{还可开启新类别}
      CanAdd -- Y --> Add[开启新类别]
      Add --> BottomUp
      CanAdd -- N --> Full[报告容量已满]
      Full --> End([结束])
  
```

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## 附录B. EQ4. 30到EQ4. 32的推导



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$$\begin{aligned}
 |\mathbf{R}| &= \left[ \sum_{j=0}^{N-1} r_j^2 \right]^{\frac{1}{2}} = \frac{\left[ \sum_{j=0}^{N-1} (u_j + c p_j)^2 \right]^{\frac{1}{2}}}{|\mathbf{U}| + c|\mathbf{P}|} = \frac{\left[ \sum_{j=0}^{N-1} (u_j^2 + 2c u_j p_j + c^2 p_j^2) \right]^{\frac{1}{2}}}{1 + c|\mathbf{P}|} \\
 &= \frac{\left[ \sum_{j=0}^{N-1} u_j^2 + 2c \sum_{j=0}^{N-1} u_j p_j + c^2 \sum_{j=0}^{N-1} p_j^2 \right]^{\frac{1}{2}}}{1 + c|\mathbf{P}|} = \frac{\left[ |\mathbf{U}|^2 + c^2 |\mathbf{P}|^2 + 2c \sum_{j=0}^{N-1} u_j p_j \right]^{\frac{1}{2}}}{1 + c|\mathbf{P}|} \\
 \because \sum_{j=0}^{N-1} u_j p_j &= \langle \mathbf{U}, \mathbf{P} \rangle = |\mathbf{P}| |\mathbf{U}| \cos(\mathbf{U}, \mathbf{P}) \\
 \therefore |\mathbf{R}| &= \frac{\left[ 1 + c^2 |\mathbf{P}|^2 + 2c |\mathbf{P}| \cos(\mathbf{U}, \mathbf{P}) \right]^{\frac{1}{2}}}{1 + c|\mathbf{P}|}
 \end{aligned}$$

Return