

Distributionally robust second-order stochastic dominance constrained optimization with Wasserstein ball

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Outline

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- Lower bound approximation
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Introduction

Basic definitions of stochastic dominance:

Definition 1 (FSD)

$X \in \mathcal{L}_p$ dominates $Y \in \mathcal{L}_p$ in the first order, denoted $X \succeq_{(1)} Y$, if

$$P\{X \leq \eta\} \leq P\{Y \leq \eta\}, \quad \forall \eta \in \mathbb{R}.$$

We define expected shortfall function

$$F_2(X; \eta) = \int_{-\infty}^{\eta} F(X; \alpha) d\alpha = \mathbb{E}[(\eta - X)_+].$$

Definition 2 (SSD)

$X \in \mathcal{L}_p$ dominates $Y \in \mathcal{L}_p$ in the second order, denoted $X \succeq_{(2)} Y$, if

$$F_2(X; \eta) \leq F_2(Y; \eta), \quad \forall \eta \in \mathbb{R}.$$

Second-order stochastic dominance is particularly popular in industry since it models risk-averse preferences.

Introduction

Proposition 1

- $X \succeq_{(1)} Y$ iff $\mathbb{E}[u(X)] \geq \mathbb{E}[u(Y)]$ for all $u \in \mathcal{U}_1$, here \mathcal{U}_1 denotes the set of **all nondecreasing** functions $u: R \rightarrow R$.
- $X \succeq_{(2)} Y$ iff $\mathbb{E}[u(X)] \geq \mathbb{E}[u(Y)]$ for all $u \in \mathcal{U}_2$, here \mathcal{U}_2 denotes the set of **all concave and nondecreasing** functions $u: R \rightarrow R$.

- Dentcheva and Ruszczyński (2003) first considered optimization problem with SSD and derived the optimality conditions.
- Dentcheva and Ruszczyński (2006) developed duality relations and solved the dual problem by utilizing the piecewise linear structure of the dual functional
- Luedtke (2008) get new linear formulations for SSD with finite distributed benchmark
- Drapkin, Gollmer, Gotzes, Schultz, et al. (2011a,2011b) study cases where the random variables are induced by mixed-integer linear recourse

Introduction

Solution methods

- **Sampling approaches** are the most popular solution method (see, Dentcheva and Ruszczyński, 2003, Liu, Sun and Xu, 2016)
- **Cut plane methods** are the most efficient solution algorithm (see, e.g., Rudolf and Ruszczyński, 2003; Homem-de-Mello and Mehrotra, 2009; Sun, Xu, et al., 2013).

Strong application background in finance

- e.g., portfolio selection, index tracking applications (Dentcheva and Ruszczyński, 2006, Meskarian, Fliege and Xu 2014; Chen, Zhuang, L., 2019)

Definition and model description

Definition 3

X dominates Y robustly in the second order over a set of probability measures $\mathcal{Q} \subset \mathcal{P}$, denoted by $X \succeq_{(2)}^{\mathcal{Q}} Y$, if

$$\mathbb{E}_P[u(X)] \geq \mathbb{E}_P[u(Y)], \forall u \in \mathcal{U}, \forall P \in \mathcal{Q},$$

where \mathcal{U} is the set of all non-decreasing and concave utility functions.

We investigate the following distributionally robust SSD constrained optimization problem

$$\begin{aligned} (P_{SSD}) \quad & \min_{z \in Z} f(z) \\ & \text{s.t. } z^T \xi \geq_{(2)}^{\mathcal{Q}} z_0^T \xi. \end{aligned}$$

Problem (P_{SSD}) can be rewritten as

$$\begin{aligned} \min_{z \in Z} \quad & f(z) \\ \text{s.t.} \quad & \mathbb{E}_P[(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+] \leq 0, \forall \eta \in \mathbb{R}, \forall P \in \mathcal{Q}. \end{aligned} \quad (1)$$

Assumption

Assumption 1

Ξ is polyhedral, i.e., $\Xi = \{\xi \in \mathbb{R}^n \mid C\xi \leq d\}$, where $C \in \mathbb{R}^{l \times n}$, $d \in \mathbb{R}^l$, and $z_0^T \Xi := \{z_0^T \xi \mid \xi \in \Xi\}$ is a compact set.

Problem (1) can be formulated as

$$\begin{aligned}
 \min_{z \in Z} \quad & f(z) \\
 \text{s.t.} \quad & \mathbb{E}_P[(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+] \leq 0, \quad \forall \eta \in \mathcal{R} := z_0^T \Xi, \quad \forall P \in \mathcal{Q}.
 \end{aligned} \tag{2}$$

Introduction

Ambiguity sets in DRO

- **Moment-based ambiguity sets** (see, Zymler, Kuhn and Rustem, 2013)
- **Distance-based ambiguity sets**
 - Kullback-Leibler divergence (see, Hu, Hong, 2014; L., Lisser and Chen, 2019)
 - ϕ -divergence (see, Jiang and Guan, 2016)
 - Wasserstein distance (see, Gao and Kleywegt, 2016, Esfahani and Kuhn, 2015, 2018, Chen, Kuhn and Wiesemann, 2018, Ji and Lejeune, 2020, Xie, 2021)
- **Mixture distribution ambiguity sets...** (see Zhu et al. 2014, Chen, Peng, L., 2018)

Related works

Distributional robustness + Stochastic dominance

- Dentcheva and Ruszczyński (2010) introduced distributionally robust SD and establish the optimality conditions.
- Dupačová and Kopa (2014) modeled the ambiguity of the distribution by a linear combination of a nominal distribution and a known contamination distribution with the combination parameter being in a parametric uncertainty set.
- Guo, Xu and Zhang (2017) proposed a discrete approximation scheme for the moment-based ambiguity sets and approximately solved the resulting stochastic optimization problem with distributionally robust SSD constraints.
- Chen and Jiang (2018) and Zhang et al. (2021) studied stability of DRO problems with k th order SD constraints induced by full random recourse.

Data-driven Wasserstein ambiguity set

Our motivation: **Distributionally robust SSD + Wasserstein ball**

Definition 4

The *Kantorovich metric* $d_K: \mathcal{P}(\Xi) \times \mathcal{P}(\Xi) \rightarrow \mathbb{R}_+$ is defined via

$$d_K(P, Q) := \inf_{\pi} \left\{ \int_{\Xi^2} \|\xi_1 - \xi_2\| \pi(d\xi_1, d\xi_2) : \begin{array}{l} \pi \text{ is a joint distribution of } \xi_1 \text{ and } \xi_2 \\ \text{with marginals } P \text{ and } Q, \text{ respectively} \end{array} \right\}.$$

Given N observations $\{\widehat{\xi}_i\}_{i=1}^N$ of ξ , we define the data-driven Wasserstein ambiguity set \mathcal{Q} as a ball centered at the empirical distribution

$$\widehat{P}_N = \frac{1}{N} \sum_{i=1}^N \delta_{\widehat{\xi}_i},$$

$$\mathcal{Q} := \{P \in \mathcal{P}(\Xi) : d_K(P, \widehat{P}_N) \leq \epsilon\}. \quad (3)$$

Main difficulties

- The **semi-infiniteness** induced from both the SSD and the distributionally robust counterpart are the main challenge.
- Distributionally robust SSD constraints are **non-smooth** such that gradient based methods fail to work here.
- Compared to moment-based ambiguity sets, the Wasserstein distance contains an extra optimization problem on computing the optimal transportation from the true distribution to the nominal distribution. Such an inner-level optimization problem leads a **min-max-min structure and non-convexity** of the distributionally robust SSD constraints.

Contributions

- Lower bound approximation:
 - use **sample approximation** approach
 - establish the **quantitative convergency** of the approximation
- Upper bound approximation:
 - propose a novel **split-and-dual decomposition** framework
 - prove convergency of approximation approach and **quantitatively estimate the approximation error**
- Peng and Delage (2020) find lower bound by sampling approach; upper bound by reformulation as a multistage robust optimization problem.

Strong duality

Gao and Kleywegt (2016)

Lemma 5

If $\Psi(\xi)$ is proper, continuous, and for some $\zeta \in \Xi$, the growth rate $\kappa := \limsup_{\|\xi - \zeta\| \rightarrow \infty} \frac{\Psi(\xi) - \Psi(\zeta)}{\|\xi - \zeta\|} < \infty$, then the optimal values of

$$\sup_{P \in \mathcal{P}(\Xi)} \left\{ \int_{\Xi} \Psi(\xi) P(d\xi) : d_K(P, \widehat{P}_N) \leq \epsilon \right\}$$

and

$$\min_{\lambda \geq 0} \left\{ \lambda \epsilon + \frac{1}{N} \sum_{i=1}^N \sup_{\xi \in \Xi} [\Psi(\xi) - \lambda \|\xi - \widehat{\xi}_i\|] \right\} \quad (4)$$

are equal. Moreover, the optimal solution set of (4) is nonempty and compact.

Lower bound approximation

Let $\Xi_N = \{\bar{\xi}_j\}_{j=1}^N$ be a set of finite samples in Ξ and $\Gamma_M = \{\eta_k\}_{k=1}^M$ be a set of finite samples in $\mathcal{R} = [\mathcal{R}_{\min}, \mathcal{R}_{\max}]$.

We then approximate the ambiguity set Q by the following Wasserstein ball:

$$Q_N := \{P \in \mathcal{P}(\Xi_N) : d_K(P, \widehat{P}_N) \leq \epsilon\}.$$

We have a lower bound approximation of problem (2):

$$\begin{array}{ll} \min_{z \in Z} & f(z) \\ \text{s.t.} & \mathbb{E}_P[(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+] \leq 0, \forall \eta \in \Gamma_M, \forall P \in Q_N. \end{array} \quad (5)$$

Tractability of the lower bound approximation

By Lemma 5 and introducing auxiliary variables, we have a linear programming reformulation of problem (5)

$$\begin{aligned}
 & \min_{z, \lambda, \beta, s} f(z) \\
 & \text{s.t.} \quad \lambda_k \in - \sum_{i=1}^N \frac{1}{N} \beta_{ik} \leq 0, \quad k = 1, \dots, \mathcal{M}, \\
 (P_{SSD-L}) \quad & \beta_{ik} + s_{jk} \leq \lambda_k \|\bar{\xi}_j - \widehat{\xi}_i\| + (\eta_k - z_0^T \bar{\xi}_j)_+, \\
 & \quad i = 1, \dots, N, j = 1, \dots, \mathcal{N}, k = 1, \dots, \mathcal{M}, \\
 & s_{jk} \geq \eta_k - z^T \bar{\xi}_j, \quad j = 1, \dots, \mathcal{N}, k = 1, \dots, \mathcal{M}, \\
 & z \in Z, \lambda \in \mathbb{R}_+^{\mathcal{M}}, \beta \in \mathbb{R}^{N \times \mathcal{M}}, s \in \mathbb{R}_+^{N \times \mathcal{M}}.
 \end{aligned}$$

Quantitative analysis of the lower approximation

Assumption 2

There exist a point $\bar{z} \in Z$ and a constant $\theta > 0$ such that

$$\sup_{\eta \in \mathcal{R}} \sup_{P \in \mathcal{Q}} \mathbb{E}_P[(\eta - \bar{z}^T \xi)_+ - (\eta - z_0^T \xi)_+] < -\theta;$$

$\lim_{N \rightarrow \infty} \alpha_N = 0$ and $\lim_{M \rightarrow \infty} \gamma_M = 0$, where $\alpha_N := \sup_{\xi \in \Xi} \inf_{\xi' \in \Xi_N} \|\xi - \xi'\|$ and Γ_M by $\gamma_M := \sup_{\eta \in \mathcal{R}} \inf_{\eta' \in \Gamma_M} |\eta - \eta'|$.

Quantitative analysis of the lower approximation

Theorem 6

Given Assumption 2, the following assertions hold.

(i) For any N and M ,

$$\mathbb{H}(\mathcal{F}_{N,M}, \mathcal{F}) \leq \frac{2D_Z}{\theta} (L\alpha_N + \gamma_M).$$

(ii) $\lim_{\substack{N \rightarrow \infty \\ M \rightarrow \infty}} v_{N,M} = v$ and $\limsup_{\substack{N \rightarrow \infty \\ M \rightarrow \infty}} \mathcal{S}_{N,M} \subset \mathcal{S}$.

(iii) If, in addition, the objective function f is Lipschitz continuous with modulus L_f , then for any N and M ,

$$|v_{N,M} - v| \leq \frac{2D_Z L_f}{\theta} (L\alpha_N + \gamma_M).$$

Moreover, if there exists a positive constant ρ such that $f(z) - v \geq \rho d(z, \mathcal{S})^2, \forall z \in \mathcal{F}$, then for sufficiently large N and M ,

$$\mathbb{D}(\mathcal{S}_{N,M}, \mathcal{S}) \leq \left(\sqrt{\frac{2D_Z}{\theta}} + \sqrt{\frac{4L_f D_Z}{\rho \theta}} \right) \sqrt{L\alpha_N + \gamma_M}. \quad (6)$$

Cutting-plane method

Algorithm 3.1 Cutting-plane Method

Start from $\iota = 1$ and $\mathcal{J}_1^\iota = \mathcal{J}_2^\iota = \emptyset$.

while $\iota \geq 1$ **do**

Solve the approximate problem:

$$\begin{aligned}
 & \min_{z, \lambda, \beta, s} f(z) \\
 & \text{s.t. } \beta_{ik} + s_{jk} \leq \lambda_k \|\bar{\xi}_j - \hat{\xi}_i\| + (\eta_k - z_0^T \bar{\xi}_j)_+, i = 1, \dots, N, j \in \mathcal{J}_1^\iota, k \in \mathcal{J}_2^\iota, \\
 (3.9) \quad & s_{jk} \geq \eta_k - z^T \bar{\xi}_j, j \in \mathcal{J}_1^\iota, k \in \mathcal{J}_2^\iota, \\
 & (3.8b), z \in Z, \lambda \in \mathbb{R}_+^{\mathcal{M}}, \beta \in \mathbb{R}^{N \times \mathcal{M}}, s \in \mathbb{R}_+^{N \times \mathcal{M}}.
 \end{aligned}$$

Let $(z^\iota, \lambda^\iota, \beta^\iota, s^\iota)$ denote the optimal solution of problem (3.9).

Calculate

$$\delta^\iota := \max_{\substack{i \in \{1, \dots, N\}, j \in \{1, \dots, \mathcal{N}\}, \\ k \in \{1, \dots, \mathcal{M}\}}} \left\{ \beta_{ik}^\iota - \lambda_k^\iota \|\bar{\xi}_j - \hat{\xi}_i\| + (\eta_k - (z^\iota)^T \bar{\xi}_j)_+ - (\eta_k - z_0^T \bar{\xi}_j)_+ \right\}.$$

if $\delta^\iota \leq 0$ **then**

Stop.

else

Determine

$$\begin{aligned}
 & (i^\iota, j^\iota, k^\iota) \in \\
 & \underset{\substack{i \in \{1, \dots, N\}, j \in \{1, \dots, \mathcal{N}\}, \\ k \in \{1, \dots, \mathcal{M}\}}}{\operatorname{argmax}} \left\{ \beta_{ik}^\iota - \lambda_k^\iota \|\bar{\xi}_j - \hat{\xi}_i\| + (\eta_k - (z^\iota)^T \bar{\xi}_j)_+ - (\eta_k - z_0^T \bar{\xi}_j)_+ \right\}.
 \end{aligned}$$

Let $\mathcal{J}_1^{\iota+1} = \mathcal{J}_1^\iota \cup j^\iota$, $\mathcal{J}_2^{\iota+1} = \mathcal{J}_2^\iota \cup k^\iota$ and $\iota \leftarrow \iota + 1$.

end if

end while

Upper bound approximation

Notice that problem (2) can be rewritten as

$$\begin{aligned} \min_{z \in Z} \quad & f(z) \\ \text{s.t.} \quad & \sup_{P \in Q} \sup_{\eta \in \mathcal{R}} \mathbb{E}_P[(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+] \leq 0. \end{aligned} \quad (7)$$

If we exchange the order of operators $\sup_{\eta \in \mathcal{R}}$ and \mathbb{E}_P in problem (7), we obtain an upper bound approximation for problem (7). However, such an upper bound approximation might be loose or even infeasible since the gap

$$\mathbb{E}_P \left[\sup_{\eta \in \mathcal{R}} \{(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+\} \right] - \sup_{\eta \in \mathcal{R}} \mathbb{E}_P[(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+] \quad (8)$$

might be large. **The larger the range \mathcal{R} of η , the larger the gap in (8).** As an extreme case, when \mathcal{R} reduces to a singleton, the gap (8) becomes 0.

Split-and-dual framework

In detail, we **divide** $\mathcal{R} = [\mathcal{R}_{\min}, \mathcal{R}_{\max}]$ into \mathcal{K} **intervals** with disjoint interiors, $[\underline{\eta}_k, \bar{\eta}_k]$, $k = 1, \dots, \mathcal{K}$, where the boundary points of the intervals are specified by $\underline{\eta}_k = \mathcal{R}_{\min} + (k-1) \frac{\mathcal{R}_{\max} - \mathcal{R}_{\min}}{\mathcal{K}}$, $\bar{\eta}_k = \mathcal{R}_{\min} + k \frac{\mathcal{R}_{\max} - \mathcal{R}_{\min}}{\mathcal{K}}$, $k = 1, \dots, \mathcal{K}$. Problem (7) can be reformulated as

$$\begin{aligned} \min_{z \in Z} \quad & f(z) \\ \text{s.t.} \quad & \sup_{P \in \mathcal{Q}} \max_{1 \leq k \leq \mathcal{K}} \sup_{\eta \in [\underline{\eta}_k, \bar{\eta}_k]} \mathbb{E}_P[(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+] \leq 0, \end{aligned}$$

Exchanging the order of operators $\sup_{\eta \in [\underline{\eta}_k, \bar{\eta}_k]}$ and \mathbb{E}_P , we have the following approximation problem

$$\begin{aligned} \min_{z \in Z} \quad & f(z) \\ \text{s.t.} \quad & \sup_{P \in \mathcal{Q}} \mathbb{E}_P \left[\sup_{\eta \in [\underline{\eta}_k, \bar{\eta}_k]} \{(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+\} \right] \leq 0, \quad k = 1, \dots, \mathcal{K}. \end{aligned} \tag{9}$$

Reformulation of the upper approximation

By applying Lemma 5, we have a reformulation of problem (9)

$$\min_{z \in Z, \lambda \in \mathbb{R}_+^{\mathcal{K}}} f(z) \quad (10a)$$

$$\text{s.t.} \quad \lambda_k \epsilon + \frac{1}{N} \sum_{i=1}^N \sup_{\xi \in \Xi} \left\{ \right. \quad (10b)$$

$$\left. \sup_{\eta \in [\underline{\eta}_k, \bar{\eta}_k]} \{(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+\} - \lambda_k \|\xi - \widehat{\xi}_i\| \right\} \leq 0, \quad k = 1, \dots, \mathcal{K}.$$

We write (10b) as

$$\lambda_k \epsilon + \frac{1}{N} \sum_{i=1}^N V_S^{ik} \leq 0, \quad k = 1, \dots, \mathcal{K}, \quad (11)$$

where

$$V_S^{ik} := \sup_{(\xi, \eta) \in \Xi \times [\underline{\eta}_k, \bar{\eta}_k]} (\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+ - \lambda_k \|\xi - \widehat{\xi}_i\|, \quad i = 1, \dots, N, \quad k = 1, \dots, \mathcal{K}.$$

We can split the problem into two convex sub-problems:

$$\begin{array}{ll}
 V_{S1}^{ik} = & \sup_{\xi, \eta, s, m} \quad \eta - z^T \xi - s - \lambda_k m \\
 & \text{s.t.} \quad s \geq \eta - z_0^T \xi, \\
 & \quad \eta - z^T \xi \geq 0, \\
 (P_{SSD-1}^{ik}) \quad & C\xi \leq d, \\
 & s \geq 0, \\
 & \eta \geq \underline{\eta}_k, \\
 & \eta \leq \bar{\eta}_k, \\
 & \|\xi - \widehat{\xi}_i\| \leq m.
 \end{array}
 \qquad
 \begin{array}{ll}
 V_{S2}^{ik} = & \sup_{\xi, \eta, s, m} \quad -s - \lambda_k m \\
 & \text{s.t.} \quad s \geq \eta - z_0^T \xi, \\
 & \quad \eta - z^T \xi \leq 0, \\
 (P_{SSD-2}^{ik}) \quad & C\xi \leq d, \\
 & s \geq 0, \\
 & \eta \geq \underline{\eta}_k, \\
 & \eta \leq \bar{\eta}_k, \\
 & \|\xi - \widehat{\xi}_i\| \leq m.
 \end{array}$$

And we have

$$V_S^{ik} = \max\{V_{S1}^{ik}, V_{S2}^{ik}\}. \quad (12)$$

Conic duality

$$\begin{aligned}
 \tilde{V}_{S1}^{ik} &= \inf_{\mu, \nu} d^T \nu - \widehat{\xi}_i^T (z - \mu_1 z_0 + \mu_2 z + C^T \nu) - \mu_3 \underline{\eta}_k + (1 - \mu_1 + \mu_2 + \mu_3) \bar{\eta}_k \\
 (D_{SSD-1}^{ik}) \quad &\text{s.t. } \mu_1 \leq 1, \quad 1 - \mu_1 + \mu_2 + \mu_3 \geq 0, \\
 &\quad \|z - \mu_1 z_0 + \mu_2 z + C^T \nu\| \leq \lambda_k, \\
 &\quad \mu \in \mathbb{R}_+^3, \quad \nu \in \mathbb{R}_+^l.
 \end{aligned}$$

$$\begin{aligned}
 \tilde{V}_{S2}^{ik} &= \inf_{\mu, \nu} d^T \nu - \widehat{\xi}_i^T (-\mu_1 z_0 - \mu_2 z + C^T \nu) - \mu_3 \underline{\eta}_k + (-\mu_1 - \mu_2 + \mu_3) \bar{\eta}_k \\
 (D_{SSD-2}^{ik}) \quad &\text{s.t. } \mu_1 \leq 1, \quad -\mu_1 - \mu_2 + \mu_3 \geq 0, \\
 &\quad \|-\mu_1 z_0 - \mu_2 z + C^T \nu\| \leq \lambda_k, \\
 &\quad \mu \in \mathbb{R}_+^3, \quad \nu \in \mathbb{R}_+^l.
 \end{aligned}$$

Upper bound

Theorem 7

Given Assumption 1, the optimal value of the following optimization problem

$$\min f(z)$$

$$\text{s.t. } \lambda_k \epsilon + \frac{1}{N} \sum_{i=1}^N v^{ik} \leq 0, \quad k = 1, \dots, \mathcal{K},$$

$$(P_{SSD-U}) \left. \begin{aligned} & \mu_1^{ik} \leq 1, \tilde{\mu}_1^{ik} \leq 1, 1 - \mu_1^{ik} + \mu_2^{ik} + \mu_3^{ik} \geq 0, -\tilde{\mu}_1^{ik} - \tilde{\mu}_2^{ik} + \tilde{\mu}_3^{ik} \geq 0, \\ & V^{ik} \geq d^T v^{ik} - \widehat{\xi}_i^T (z - \mu_1^{ik} z_0 + \mu_2^{ik} z + C^T v^{ik}) - \mu_3^{ik} \eta_k + (1 - \mu_1^{ik} + \mu_2^{ik} + \mu_3^{ik}) \bar{\eta}_k, \\ & V^{ik} \geq d^T \tilde{v}^{ik} - \widehat{\xi}_i^T (-\tilde{\mu}_1^{ik} z_0 - \tilde{\mu}_2^{ik} z + C^T \tilde{v}^{ik}) - \tilde{\mu}_3^{ik} \eta_k + (-\tilde{\mu}_1^{ik} - \tilde{\mu}_2^{ik} + \tilde{\mu}_3^{ik}) \bar{\eta}_k, \\ & \|z - \mu_1^{ik} z_0 + \mu_2^{ik} z + C^T v^{ik}\| \leq \lambda_k, \quad \|-\tilde{\mu}_1^{ik} z_0 - \tilde{\mu}_2^{ik} z + C^T \tilde{v}^{ik}\| \leq \lambda_k, \\ & \mu^{ik} \in \mathbb{R}_+^3, v^{ik} \in \mathbb{R}^l, \tilde{\mu}^{ik} \in \mathbb{R}_+^3, \tilde{v}^{ik} \in \mathbb{R}^l, V^{ik} \in \mathbb{R}, \end{aligned} \right\}$$

$$i = 1, \dots, N, \quad k = 1, \dots, \mathcal{K},$$

$$z \in Z, \lambda \in \mathbb{R}_+^{\mathcal{K}}.$$

is an upper bound to that of problem (P_{SSD}) .

Quantitative analysis of the upper approximation

Let

$$g(z, \mathcal{K}) := \max_{1 \leq k \leq \mathcal{K}} \sup_{P \in \mathcal{Q}} \mathbb{E}_P \left[\sup_{\eta \in [\underline{\eta}_k, \bar{\eta}_k]} \left\{ (\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+ \right\} \right],$$

$$\begin{aligned} g(z) &:= \sup_{P \in \mathcal{Q}} \sup_{\eta \in \mathcal{R}} \mathbb{E}_P \left[(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+ \right] \\ &= \max_{1 \leq k \leq \mathcal{K}} \sup_{P \in \mathcal{Q}} \sup_{\eta \in [\underline{\eta}_k, \bar{\eta}_k]} \mathbb{E}_P \left[(\eta - z^T \xi)_+ - (\eta - z_0^T \xi)_+ \right]. \end{aligned}$$

Proposition 2

Given Assumption 1, for any positive integer \mathcal{K} , $g(\cdot, \mathcal{K})$ and $g(\cdot)$ are Lipschitz continuous with modulus $C = \sup_{P \in \mathcal{Q}} \mathbb{E}_P[\|\xi\|] < \infty$.

Proposition 3

Given Assumption 1, we have that $g(z, \mathcal{K}) - g(z) \leq 2 \frac{\mathcal{R}_{\max} - \mathcal{R}_{\min}}{\mathcal{K}}$, and $\lim_{\mathcal{K} \rightarrow \infty} g(z, \mathcal{K}) = g(z)$, uniformly with respect to $z \in Z$.

Non-differentiable MFCQ

Definition 8

(ND-MFCQ) Let $F(t) := \{x \in \mathbb{R}^n \mid g_j(x, t) \leq 0, j \in J\}$ with subdifferentiable g_j , here t is the parameter in the constraints. Given \bar{t} and $\bar{x} \in F(\bar{t})$, if there exist some vector θ and real constants $\sigma < 0$, $\alpha_1 > 0$, $\alpha_2 > 0$ such that

$$\langle \zeta, \theta \rangle \leq \sigma < 0, \forall \zeta \in \partial g_j(x, t), \forall x : \|x - \bar{x}\| \leq \alpha_1, \forall t : \|t - \bar{t}\| \leq \alpha_2, \forall j \in J_0(\bar{x}, \bar{t}),$$

where $J_0(\bar{x}, \bar{t}) := \{j \in J \mid g_j(\bar{x}, \bar{t}) = 0\}$, then we say that non-differentiable MFCQ (ND-MFCQ) holds at (\bar{x}, \bar{t}) with θ, σ, α_1 and α_2 ,

ND-MFCQ is equivalent to MFCQ if differentiable

Quantitative analysis of the upper approximation

Assumption 3

The optimal solution set of problem (9) with $\mathcal{K} = 1$, denoted by \mathcal{S}_1 , is nonempty.

Theorem 9

Given Assumptions 1 and 3. For some $z^* \in \mathcal{S}$, assume that ND-MFCQ holds at $(z^*, 0)$ with θ , σ , α_1 , and α_2 as is defined in Definition 8. If the objective function f is Lipschitz continuous with modulus L_f , then for $\mathcal{K} \geq \max \left\{ \frac{1}{\alpha_2}, \frac{2}{|\sigma|} \frac{\mathcal{R}_{\max} - \mathcal{R}_{\min}}{\alpha_1} \|\theta\|, -2 \frac{\mathcal{R}_{\max} - \mathcal{R}_{\min}}{g(z^*)} \left(C \frac{\|\theta\|}{|\sigma|} + 1 \right) \right\}$, we have that

$$|v_{\mathcal{K}} - v| \leq L_f \frac{2\|\theta\|}{|\sigma|} \frac{\mathcal{R}_{\max} - \mathcal{R}_{\min}}{\mathcal{K}},$$

and $\lim_{\mathcal{K} \rightarrow \infty} v_{\mathcal{K}} = v$.

Upper bound

Theorem 10

Given Assumption 1, the optimal value of the following optimization problem

$$\min f(z)$$

$$\text{s.t. } \lambda_k \epsilon + \frac{1}{N} \sum_{i=1}^N v^{ik} \leq 0, \quad k = 1, \dots, \mathcal{K},$$

$$(P_{SSD-U}) \left. \begin{aligned} & \mu_1^{ik} \leq 1, \tilde{\mu}_1^{ik} \leq 1, 1 - \mu_1^{ik} + \mu_2^{ik} + \mu_3^{ik} \geq 0, -\tilde{\mu}_1^{ik} - \tilde{\mu}_2^{ik} + \tilde{\mu}_3^{ik} \geq 0, \\ & V^{ik} \geq d^T v^{ik} - \widehat{\xi}_i^T (z - \mu_1^{ik} z_0 + \mu_2^{ik} z + C^T v^{ik}) - \mu_3^{ik} \eta_k + (1 - \mu_1^{ik} + \mu_2^{ik} + \mu_3^{ik}) \bar{\eta}_k, \\ & \tilde{V}^{ik} \geq d^T \tilde{v}^{ik} - \widehat{\xi}_i^T (-\tilde{\mu}_1^{ik} z_0 - \tilde{\mu}_2^{ik} z + C^T \tilde{v}^{ik}) - \tilde{\mu}_3^{ik} \eta_k + (-\tilde{\mu}_1^{ik} - \tilde{\mu}_2^{ik} + \tilde{\mu}_3^{ik}) \bar{\eta}_k, \\ & \|z - \mu_1^{ik} z_0 + \mu_2^{ik} z + C^T v^{ik}\| \leq \lambda_k, \quad \|-\tilde{\mu}_1^{ik} z_0 - \tilde{\mu}_2^{ik} z + C^T \tilde{v}^{ik}\| \leq \lambda_k, \\ & \mu^{ik} \in \mathbb{R}_+^3, v^{ik} \in \mathbb{R}^l, \tilde{\mu}^{ik} \in \mathbb{R}_+^3, \tilde{v}^{ik} \in \mathbb{R}^l, V^{ik} \in \mathbb{R}, \end{aligned} \right\}$$

$$i = 1, \dots, N, \quad k = 1, \dots, \mathcal{K},$$

$$z \in Z, \lambda \in \mathbb{R}_+^{\mathcal{K}}.$$

is an upper bound to that of problem (P_{SSD}) .

Sequential convex approximation

Algorithm 4.1 Sequential convex approximation

Start from $z^t \in Z$, $t = 1$.

while $t \geq 1$ **do**

Solve problem (P_{SSD-U}) with an additional constraint $z = z^t$. Denote the optimal $\mu, \tilde{\mu}$ by $\mu^t, \tilde{\mu}^t$, respectively.

Solve problem (P_{SSD-U}) with additional constraints $\mu = \mu^t, \tilde{\mu} = \tilde{\mu}^t$. Denote the optimal z by z^{t+1} .

if $z^{t+1} = z^t$ **then**

Break.

else

$t \leftarrow t + 1$.

end if

end while

Numerical results

Table: The optimal values and the optimal solutions of the lower and upper bound approximations

lower bound approximation ((P_{SSD-L}) or Algorithm 3.1)				upper bound approximation (Algorithm 4.1)			Gap
\mathcal{N}	\mathcal{M}	Optimal value	Optimal solution	\mathcal{K}	Optimal value	Optimal solution	
100	100	0.2922	$(0.4229, 0.4027)^T$	10	0.4097	$(0.8010, 0.1564)^T$	40.2122%
200	200	0.2964	$(0.4266, 0.4077)^T$	11	0.3044	$(0.4590, 0.4002)^T$	2.6991%
300	300	0.3014	$(0.4423, 0.4014)^T$	12	0.3025	$(0.4653, 0.3868)^T$	0.3650%

Numerical results

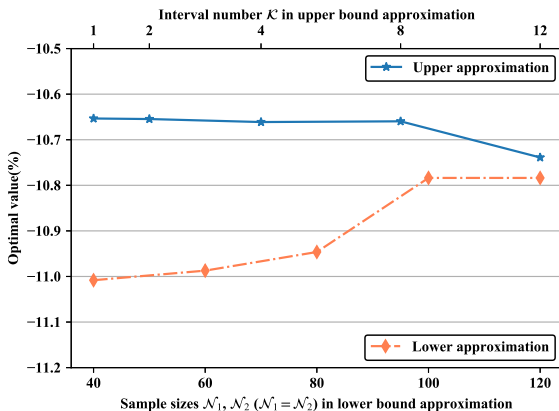


Figure: Optimal values of the lower bound approximation with respect to \mathcal{N}, \mathcal{M} and that of the upper bound approximation with respect to \mathcal{K} .

Numerical results

Table: Optimal values of the lower and upper bound approximations, and their relative gaps with respect to different robust radii.

Robust radius ϵ	Optimal values (%)		Gap
	lower bound approximation	upper bound approximation	
10^{-5}	-10.8775	-10.8268	0.4661%
10^{-4}	-10.7838	-10.7389	0.4164%
10^{-3}	-10.7836	-10.6536	1.2055%
10^{-2}	-10.7823	-10.6535	1.1946%
0.1	-10.7689	-10.6534	1.0725%
0.5	-10.6885	-10.6534	0.3284%
1	-10.6534	-10.6534	0%

Conclusions

Summary:

- Study a distributionally robust SSD constrained optimization problem
- Adopt the sample approximation approach to develop a linear programming formulation to obtain a lower bound approximation
- Establish the quantitative convergency for the lower bound approximation problem
- Propose a novel split-and-dual decomposition framework to derive an upper bound approximation
- Quantitatively estimate the approximation error between the optimal value of the upper bound approximation and that of the original problem

Further works:

- Modifying the design of [cutting-planes](#)
- Investigate [the critical number of intervals](#) for enhancing the practicality of the upper bound approximation
- Consider distributionally robust [multivariate](#) robust SSD constrained optimization problem

Thank you!